

Direct calculation of hadronic light-by-light scattering

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Outline

1. Introduction
2. Lattice four-point function
3. Light-by-light scattering amplitude
4. Strategy for $g - 2$
5. Summary and outlook

Some of these results were posted in [arXiv:1507.01577](https://arxiv.org/abs/1507.01577)

The muon $g - 2$

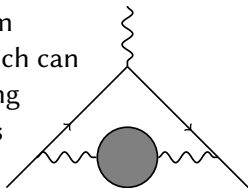
One of the most precise tests of the Standard Model

$$a_\mu \equiv \left(\frac{g - 2}{2} \right)_\mu = \begin{cases} 116592080(63) \times 10^{-11} & \text{experiment} \\ 116591790(65) \times 10^{-11} & \text{theory} \end{cases}$$

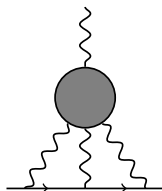
$\delta a_\mu = (290 \pm 90) \times 10^{-11}$, a 3σ deviation

- ▶ Fermilab 989 has goal to reduce experimental error by factor of 4
- ▶ Leading theory errors come from:

Hadronic vacuum polarization, which can be improved using $e^+e^- \rightarrow$ hadrons experiments

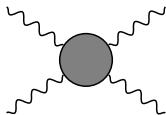


Hadronic light-by-light (HLbL) scattering, which is not easily obtained from experiments



Light-by-light scattering

Before computing a_{μ}^{HLbL} , start by studying light-by-light scattering by itself.



This has much more information than just a_{μ}^{HLbL} . We can:

- ▶ Compare against phenomenology.
- ▶ Test models used to compute a_{μ}^{HLbL} .

Lattice four-point function

Directly compute four-point function of vector currents

- ▶ Use one local current $Z_V J_\mu^l$ at the source point.
- ▶ Use three conserved currents J_μ^c .

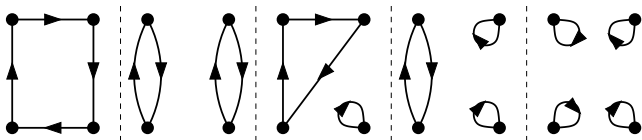
In position space:

$$\begin{aligned} \Pi_{\mu_1 \mu_2 \mu_3 \mu_4}^{\text{pos}}(\mathbf{x}_1, \mathbf{x}_2, 0, \mathbf{x}_4) = & \left\langle Z_V J_{\mu_3}^l(0) [J_{\mu_1}^c(\mathbf{x}_1) J_{\mu_2}^c(\mathbf{x}_2) J_{\mu_4}^c(\mathbf{x}_4) \right. \\ & + \delta_{\mu_1 \mu_2} \delta_{\mathbf{x}_1 \mathbf{x}_2} T_{\mu_1}(\mathbf{x}_1) J_{\mu_4}^c(\mathbf{x}_4) \\ & + \delta_{\mu_1 \mu_4} \delta_{\mathbf{x}_1 \mathbf{x}_4} T_{\mu_4}(\mathbf{x}_4) J_{\mu_2}^c(\mathbf{x}_2) \\ & + \delta_{\mu_2 \mu_4} \delta_{\mathbf{x}_2 \mathbf{x}_4} T_{\mu_4}(\mathbf{x}_4) J_{\mu_1}^c(\mathbf{x}_1) \\ & \left. + \delta_{\mu_1 \mu_4} \delta_{\mu_2 \mu_4} \delta_{\mathbf{x}_1 \mathbf{x}_4} \delta_{\mathbf{x}_2 \mathbf{x}_4} J_{\mu_4}^c(\mathbf{x}_4) \right] \rangle, \end{aligned}$$

where $T_\mu(x)$ is a “tadpole” contact operator. This satisfies the conserved-current relations,

$$\Delta_{\mu_1}^{x_1} \Pi_{\mu_1 \mu_2 \mu_3 \mu_4}^{\text{pos}} = \Delta_{\mu_2}^{x_2} \Pi_{\mu_1 \mu_2 \mu_3 \mu_4}^{\text{pos}} = \Delta_{\mu_4}^{x_4} \Pi_{\mu_1 \mu_2 \mu_3 \mu_4}^{\text{pos}} = 0.$$

Quark contractions

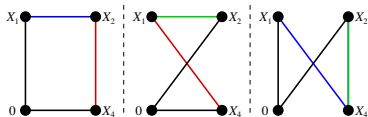


Compute only the *fully-connected* contractions, with fixed kernels summed over x_1 and x_2 :

$$\Pi_{\mu_1 \mu_2 \mu_3 \mu_4}^{\text{pos}'}(x_4; f_1, f_2) = \sum_{x_1, x_2} f_1(x_1) f_2(x_2) \Pi_{\mu_1 \mu_2 \mu_3 \mu_4}^{\text{pos}}(x_1, x_2, 0, x_4)$$

Generically, need the following propagators:

- ▶ 1 point-source propagator from $x_3 = 0$
- ▶ 8 sequential propagators through x_1 , for each μ_1 and f_1 or f_1^*
- ▶ 8 sequential propagators through x_2
- ▶ 32 double-sequential propagators through x_1 and x_2 , for each (μ_1, μ_2) and (f_1, f_2) or (f_1^*, f_2^*)



Kinematical setup

Obtain momentum-space Euclidean four-point function using plane waves:

$$\Pi_{\mu_1\mu_2\mu_3\mu_4}^E(p_4; p_1, p_2) = \sum_{x_4} e^{-ip_4 \cdot x_4} \Pi_{\mu_1\mu_2\mu_3\mu_4}^{\text{pos}'}(x_4; f_1, f_2) \Big|_{f_a(x) = e^{-ip_a \cdot x}}.$$

Thus, we can efficiently fix $p_{1,2}$ and choose arbitrary p_4 .

- ▶ Full 4-point tensor is very complicated: it can be decomposed into 41 scalar functions of 6 kinematic invariants.
- ▶ Forward case is simpler:

$$Q_1 \equiv p_2 = -p_1, \quad Q_2 \equiv p_4.$$

Then there are 8 scalar functions that depend on 3 kinematic invariants.

Lattice ensembles

Use CLS ensembles: $N_f = 2$ $O(a)$ -improved Wilson, with $a = 0.063$ fm.

1. $m_\pi = 451$ MeV, 64×32^3
2. $m_\pi = 324$ MeV, 96×48^3
3. $m_\pi = 277$ MeV, 96×48^3

Keep only u and d quarks in the electromagnetic current, i.e.,

$$J_\mu^l = \frac{2}{3} \bar{u} \gamma_\mu u - \frac{1}{3} \bar{d} \gamma_\mu d.$$

Study forward case with a few different Q_1 and also more general kinematics.

Forward LbL amplitude

Take the amplitude for forward scattering of transversely polarized virtual photons,

$$\mathcal{M}_{TT}(-Q_1^2, -Q_2^2, \nu) = \frac{e^4}{4} R_{\mu_1\mu_2} R_{\mu_3\mu_4} \Pi_{\mu_1\mu_2\mu_3\mu_4}^E(-Q_2; -Q_1, Q_1),$$

where $\nu = -Q_1 \cdot Q_2$ and $R_{\mu\nu}$ projects onto the plane orthogonal to Q_1, Q_2 .

A subtracted dispersion relation at fixed spacelike Q_1^2, Q_2^2 relates this to the $\gamma^* \gamma^* \rightarrow$ hadrons cross sections $\sigma_{0,2}$:

$$\mathcal{M}_{TT}(q_1^2, q_2^2, \nu) - \mathcal{M}_{TT}(q_1^2, q_2^2, 0) = \frac{2\nu^2}{\pi} \int_{\nu_0}^{\infty} d\nu' \frac{\sqrt{\nu'^2 - q_1^2 q_2^2}}{\nu'(\nu'^2 - \nu^2 - i\epsilon)} [\sigma_0(\nu') + \sigma_2(\nu')]$$

This is model-independent and will allow for systematically improvable comparisons between lattice and experiment.

Model for $\sigma(\gamma^*\gamma^* \rightarrow \text{hadrons})$

(V. Pascalutsa, V. Pauk, M. Vanderhaeghen, Phys. Rev. D **85** (2012) 116001)

Include single mesons and $\pi^+\pi^-$ final states:

$$\sigma_0 + \sigma_2 = \sum_M \sigma(\gamma^*\gamma^* \rightarrow M) + \sigma(\gamma^*\gamma^* \rightarrow \pi^+\pi^-)$$

Mesons:

- ▶ pseudoscalar (π^0, η')
- ▶ scalar (a_0, f_0)
- ▶ axial vector (f_1)
- ▶ tensor (a_2, f_2)

$\sigma(\gamma^*\gamma^* \rightarrow M)$ depends on the meson's:

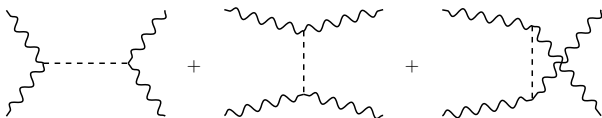
- ▶ mass m and width Γ
- ▶ two-photon decay width $\Gamma_{\gamma\gamma}$
- ▶ two-photon transition form factor $F(q_1^2, q_2^2)$

assume $F(q_1^2, q_2^2) = F(q_1^2, 0)F(0, q_2^2)/F(0, 0)$

Use scalar QED dressed with form factors for $\sigma(\gamma^*\gamma^* \rightarrow \pi^+\pi^-)$.

Aside: π^0 contribution

Leading HLbL contributions to muon $g - 2$ are expected to come from π^0 exchange diagrams, which dominate at long distances.



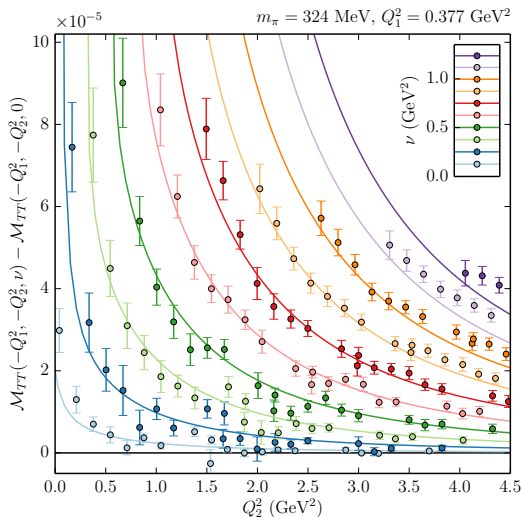
Their contribution to the four-point function:

$$\begin{aligned} & \Pi_{\mu_1 \mu_2 \mu_3 \mu_4}^{E, \pi^0}(p_4; p_1, p_2) \\ &= -p_{1\alpha} p_{2\beta} p_{3\sigma} p_{4\tau} \left(\frac{\mathcal{F}_{12} \epsilon_{\mu_1 \mu_2 \alpha \beta} \mathcal{F}_{34} \epsilon_{\mu_3 \mu_4 \sigma \tau}}{(p_1 + p_2)^2 + m_\pi^2} + \frac{\mathcal{F}_{13} \epsilon_{\mu_1 \mu_3 \alpha \sigma} \mathcal{F}_{24} \epsilon_{\mu_2 \mu_4 \beta \tau}}{(p_1 + p_3)^2 + m_\pi^2} \right. \\ & \quad \left. + \frac{\mathcal{F}_{14} \epsilon_{\mu_1 \mu_4 \alpha \tau} \mathcal{F}_{23} \epsilon_{\mu_2 \mu_3 \beta \sigma}}{(p_2 + p_3)^2 + m_\pi^2} \right), \end{aligned}$$

where $p_3 = -(p_1 + p_2 + p_4)$ and $\mathcal{F}_{ij} = \mathcal{F}(p_i^2, p_j^2)$.

This is consistent with the dispersion relation using $\sigma(\gamma^* \gamma^* \rightarrow \pi^0)$.

\mathcal{M}_{TT} : dependence on ν and Q_2^2



For scalar, tensor mesons there is no data from expt; we use

$$F(q^2, 0) = F(0, q^2) = \frac{1}{1 - q^2/\Lambda^2}$$

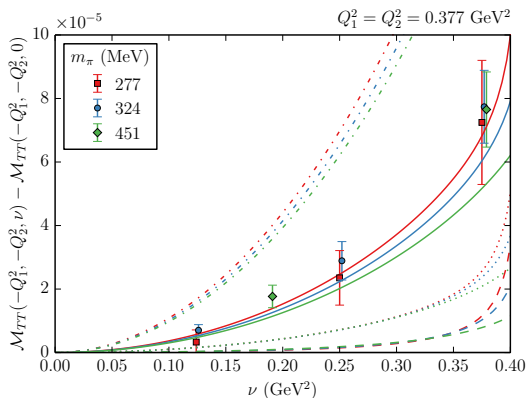
with Λ set by hand to 1.6 GeV

Changing Λ by $\pm 0.4 \text{ GeV}$ adjusts curves by up to $\pm 50\%$.

Points: lattice data.

Curves: dispersion relation + model for cross section.

\mathcal{M}_{TT} : dependence on ν and m_π



Points: lattice data.

Curves: dispersion relation +
model for cross section.

In increasing order:

- ▶ π^0
- ▶ $\pi^0 + \eta'$
- ▶ full model
- ▶ full model + high-energy $\sigma(\gamma\gamma \rightarrow \text{hadrons})$ at physical m_π

General kinematics case

To study off-forward kinematics, we fix $p_1^2 = p_2^2 = (p_1 + p_2)^2 = 0.33 \text{ GeV}^2$ and consider contractions of $\Pi_{\mu_1\mu_2\mu_3\mu_4}^E(p_4; p_1, p_2)$ with two different tensors:

1. $\delta_{\mu_1\mu_2}\delta_{\mu_3\mu_4}$ yields π^0 contribution

$$-2 \left(\frac{(p_1 \cdot p_2)(p_3 \cdot p_4) - (p_1 \cdot p_4)(p_2 \cdot p_3)}{(p_1 + p_3)^2 + m_\pi^2} \mathcal{F}(p_1^2, p_3^2) \mathcal{F}(p_2^2, p_4^2) + \frac{(p_1 \cdot p_2)(p_3 \cdot p_4) - (p_1 \cdot p_3)(p_2 \cdot p_4)}{(p_2 + p_3)^2 + m_\pi^2} \mathcal{F}(p_1^2, p_4^2) \mathcal{F}(p_2^2, p_3^2) \right),$$

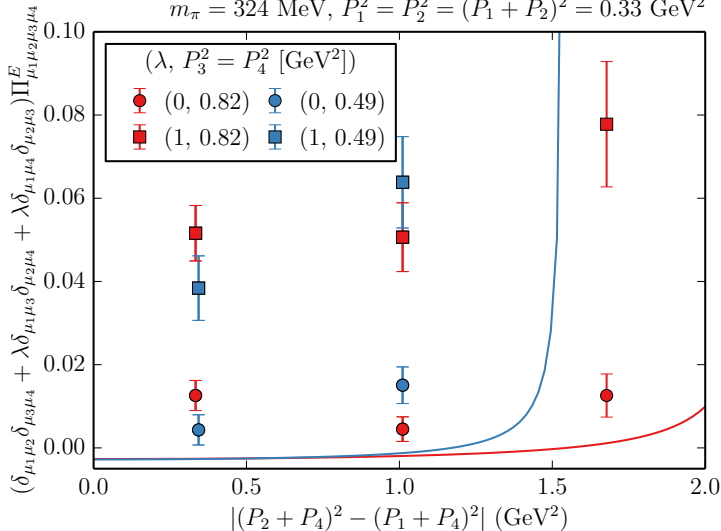
where $\mathcal{F}(0,0) = -1/(4\pi^2 F_\pi)$ (Wess-Zumino-Witten) and we use vector meson dominance for dependence on p^2 .

2. $\delta_{\mu_1\mu_2}\delta_{\mu_3\mu_4} + \delta_{\mu_1\mu_3}\delta_{\mu_2\mu_4} + \delta_{\mu_1\mu_4}\delta_{\mu_2\mu_3}$, which is totally symmetric and thus has no π^0 contribution.

We also fix $p_3^2 = p_4^2$ to two different values and plot versus the one remaining kinematic variable.

Off-forward kinematics

$$m_\pi = 324 \text{ MeV}, P_1^2 = P_2^2 = (P_1 + P_2)^2 = 0.33 \text{ GeV}^2$$



Squares: contraction without π^0 contribution.

Circles: contraction containing π^0 contribution.

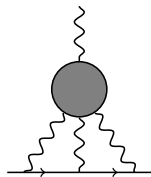
Curves: π^0 contribution assuming model for $\mathcal{F}(p_1^2, p_2^2)$.

Strategy for muon $g - 2$: kernel

In Euclidean space, give muon momentum $p = im\hat{\epsilon}$, $\hat{\epsilon}^2 = 1$.

Apply QED Feynman rules and isolate $F_2(0)$; obtain

$$a_{\mu}^{\text{HLbL}} = \int d^4x d^4y \mathcal{L}_{[\rho,\sigma];\mu\nu\lambda}(\hat{\epsilon}, x, y) i\hat{\Pi}_{\rho;\mu\nu\lambda\sigma}(x, y),$$



where
$$\hat{\Pi}_{\rho;\mu\nu\lambda\sigma}(x_1, x_2) = \int d^4x_4 (ix_4)_{\rho} \langle J_{\mu}(x_1) J_{\nu}(x_2) J_{\lambda}(0) J_{\sigma}(x_4) \rangle.$$

The integrand for a_{μ} is a scalar function of 5 invariants: x^2 , y^2 , $x \cdot y$, $x \cdot \epsilon$, and $y \cdot \epsilon$, so 3 of the 8 dimensions in the integral are trivial.

Five dimensions is still too many. Result is independent of $\hat{\epsilon}$, so we can eliminate it by averaging in the integrand:

$$\mathcal{L}(\hat{\epsilon}, x, y) \rightarrow \bar{\mathcal{L}}(x, y) \equiv \langle \mathcal{L}(\hat{\epsilon}, x, y) \rangle_{\hat{\epsilon}}$$

Then the integrand depends only on x^2 , y^2 , and $x \cdot y$.

Strategy for muon $g - 2$: lattice

$$\begin{aligned} a_{\mu}^{\text{HLbL}} &= \int d^4x \int d^4y d^4z \bar{\mathcal{L}}_{[\rho,\sigma];\mu\nu\lambda}(x,y)(-z)_{\rho} \langle J_{\mu}(x)J_{\nu}(y)J_{\lambda}(0)J_{\sigma}(z) \rangle \\ &= 2\pi^2 \int_0^{\infty} x^3 dx \int d^4y d^4z \bar{\mathcal{L}}_{[\rho,\sigma];\mu\nu\lambda}(x,y)(-z)_{\rho} \langle J_{\mu}(x)J_{\nu}(y)J_{\lambda}(0)J_{\sigma}(z) \rangle. \end{aligned}$$

Evaluate the y and z integrals in the following way:

1. Fix local currents at the origin and x , and compute point-source propagators.
2. Evaluate the integral over z using sequential propagators.
3. Contract with $\bar{\mathcal{L}}_{[\rho,\sigma];\mu\nu\lambda}(x,y)$ and sum over y .

The above has similar cost to evaluating scattering amplitudes at fixed p_1, p_2 . Do this several times to perform the one-dimensional integral over $|x|$.

Summary and outlook

- ▶ The contribution from fully-connected four-point function to the light-by-light scattering amplitude can be efficiently evaluated if two of the three momenta are fixed.
- ▶ Forward-scattering case is related to $\sigma(\gamma^* \gamma^* \rightarrow \text{hadrons})$; lattice is consistent with phenomenology, within the latter's large uncertainty.
- ▶ For typical Euclidean kinematics the π^0 contribution is not dominant.
- ▶ A strategy is in place for computing the leading-order HLbL contribution to the muon $g - 2$.
Work is ongoing to evaluate the kernel $\tilde{\mathcal{L}}_{[\rho, \sigma]; \mu\nu\lambda}(x, y)$.
- ▶ Phenomenology indicates the π^0 contribution is dominant for $g - 2$; reaching this regime (physical m_π , large volumes) may be challenging on the lattice.
- ▶ Results on the HLbL scattering amplitude were posted in arXiv:1507.01577.