

"Probabilistic aftershock forecasting: A Bayesian statistical approach



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Outline

Aftershock forecasting, and its problems

Immediate forecasting of large aftershocks within one day after the main shock

Mainshock, Aftershocks



Eqrthaueks during 1-year period before and after the Tohoku-oki (M9.0) earthquake

Mainshock, Aftershocks



Importance of Aftershock forecasting after the main shock

Aftershock

People's safety

Large aftershocks can cause additional damages in the affected area.

Aftershock forecasting has been carried out to reduce the seismic risks.

- Q6(2) (回答票6) (2)それでは、地震発生後数時間が経過した時、あなたは特にどの ようなことを知りたいと思いますか。この中から3つまであげてください。(3 M. A.)(2)数時間経過後知りたいこと
 - (12.2) (ア) 自分の住んでいる地域の震度
 - (16.2) (イ) 震源や地震の規模
 - (4.2) (ウ) 津波襲来の有無
 - (35.1) (エ) 今後の余震の見通しなど地震活動の推移
 - (30.1) (オ) 家族や親戚などの安否情報や被害情報
 - (33.7) (カ) 知人・友人などの安否情報や被害情報
 - (47.2)(キ)水道・電気・ガス・電話の被害状況と復旧の見通し
 - (39.1) (ク) 道路・電車など交通関係の被害状況と復旧の見通し
 - (16.0) (ケ) 学校や医療機関など公共施設の被害状況
 - (13.3) (コ) 会社など職場の被害状況
 - (13.6) (サ) 国、県や市区町村が実施している(実施する)対策
 - (0.3) その他
 - (1.8) 特にない Public opinion research
 - (1.4) わからない in Japan (1995)

What kind of information do you want to know a few hours after the main shock?

Damage situation and recovery period of Infrastructure

Aftershock forecasting by Japan Meteorological Agency



地震調査研究推進本部パンフレットより

Forecasting aftershocks after the main shock

Immediate forecast of aftershock is strongly required.

We need to tailor a forecast model to each aftershock sequence.



Why is immediate aftershock forecasting difficult? The data in the early period is highly deficient. Earthquakes 1995 Kobe earthquake of M 7.3 6 5 4





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Empirical law of aftershocks:

- time evolution of aftershock activity



Utsu, Ogata & Matsu'ura (1995)

Omori-law k

$$\lambda(t) = \frac{\kappa}{t+c}$$



F. Omori (1894)





T. Utsu(1961)

Empirical law of aftershocks:

- magnitude-frequency relation



Gutenberg-Richter law (1944) log N = a - bM

Exponential distribution $P(M) \propto e^{-\beta M} \ (\ \beta = b \log 10 \)$



Forecast model

(Reasenberg and Jones 1989)

The rate of earthquakes of the magnitude M at time t

$$\lambda(t, M) = \frac{K}{(t+c)^p} e^{-\beta M}$$

Omori-Utu Gutenberg-Richter

Parameter Estimation

Estimate the parameters *K*, *c*, *p* and β .

Forecast the probability

The expected number of earthquakes with magnitude M > M_c in the time interval [t_1 , t_2]

$$n = \int_{t_1}^{t_2} dt \int_{M_c}^{\infty} dM \lambda(t, M)$$

Schematic illustration of our procedure

Underlying Eqs: detected EQs. + missing EQs.



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Estimating the detection rate



Magnitude dependence of the detection rate

$$\Phi(M|\mu,\sigma) = \int_{-\infty}^{M} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} dx$$

μ: the magnitude with 50 % detection rate Observed magnitude distribution:

(G-R law) × (Detection Rate function)

Ogata & Katsura (1993).

Time dependence of the detection rate - Assume the parameter μ is a function of the time.

- Estimate μ(t) by using Bayesian smoothing method Omi et al., (2013, 2014, 2015).

2004 Chuetsu aftershock sequence

Objective Bayesian Estimation Estimate $\boldsymbol{\mu} = \{\mu_1, \mu_2, \cdots, \mu_N\} \beta_{\text{and}} \sigma_{\text{from}} \boldsymbol{M} = \{M_1, M_2, \cdots, M_N\}$ Likelihood: $P_{\beta,\sigma}(\boldsymbol{M}|\boldsymbol{\mu}) = \prod_{i=1}^{N} \beta e^{-\beta(M_i - \mu_i) - \frac{\beta^2 \sigma^2}{2}} \Phi(M_i|\mu_i, \sigma)$ Prior: $P_V(\boldsymbol{\mu}) = P(\mu_1, \mu_2) \prod_{i=1}^{N-2} \frac{1}{\sqrt{2\pi V}} e^{-\frac{(\mu_{i+2} - 2\mu_{i+1} + \mu_i)^2}{2V}}$

State Estimation: Find *µ* that maximizes the posterior p.d.f.

 $P_{\beta,\sigma,V}(\boldsymbol{\mu}|\boldsymbol{M}) \propto P_{\beta,\sigma}(\boldsymbol{M}|\boldsymbol{\mu})P_V(\boldsymbol{\mu})$ Posterior:

Likelihood Prior Parameter Estimation: Find β , σ and V that maimizes the posterior p.d.f. $P(\beta, \sigma, V | \mathbf{M}) \propto P_{\beta, \sigma, V}(\mathbf{M}) P(\beta, \sigma, V)$ Marginal Likelihood Prior

Bayesian forecasting: considering the estimation uncertainty



(Omi et al., JGR 2015)

Forecasting experiment

The aftershocks of the 2011 Tohoku-oki earthquake of M9.0 The NEIC PDE Catalog (provided by USGS)



Learning period	Forecast period
0 – 1 [day]	1-31 [day]
0 – 3 [hour]	3–6 [hour]
0-6 [hour]	6 – 12 [hour]
0 – 12 [hour]	12 – 24 [hour]
0 – 24 [hour]	24 – 48 [hour]

Forecast experiment with the 2011 Tohoku sequence



Immediate forecast with the 2011 Tohoku sequence



Bar: 95% interval



Conclusion

We proposed a method for estimating the underlying aftershock model from the deficient data of early aftershocks.

• Our method well forecasts the aftershock activity from the deficient data available a few hours after a main shock.

References

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General Discussion

 Point process models can be applicable to diverse phenomena such as earthquakes, neural spiking activity, human communication, crime occurrence (predictive policing).

Mathematical methods are useful to solve problems in the society.

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