

The Rule 54: Completely Solvable Statistical Mechanics Model of Deterministic Interacting Dynamics

Tomaž Prosen

Faculty of mathematics and physics, University of Ljubljana, Slovenia

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- Can matrix product ansatz be useful for encoding (time-dependent, or steady) states of deterministic reversible interacting systems?
- Find minimal interacting deterministic $(1 + 1)d$ model about which we can 'know everything' (without approximations and assumptions)
- Check if the model has generic physical (say transport) properties!



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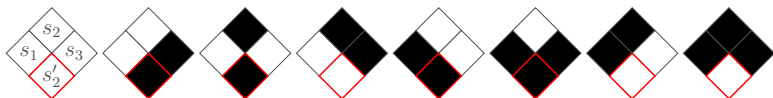
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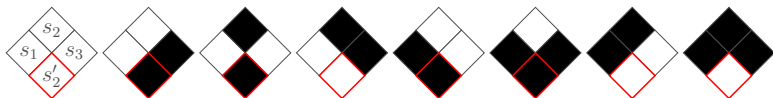


$$0 \times 2^0 + 1 \times 2^1 + 1 \times 2^2 + 0 \times 2^3 + 1 \times 2^4 + 1 \times 2^5 + 0 \times 2^6 + 0 \times 2^7 = 54$$

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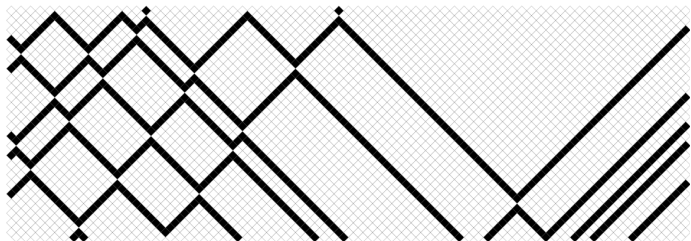


$$s'_2 = \chi(s_1, s_2, s_3) = s_1 + s_2 + s_3 + s_1 s_3 \pmod{2}$$

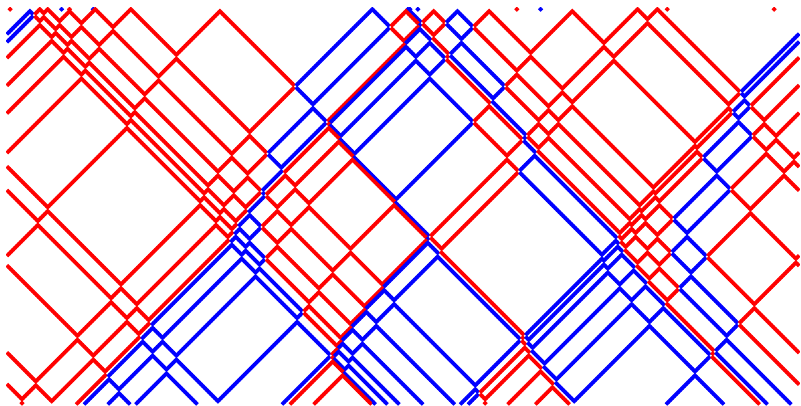


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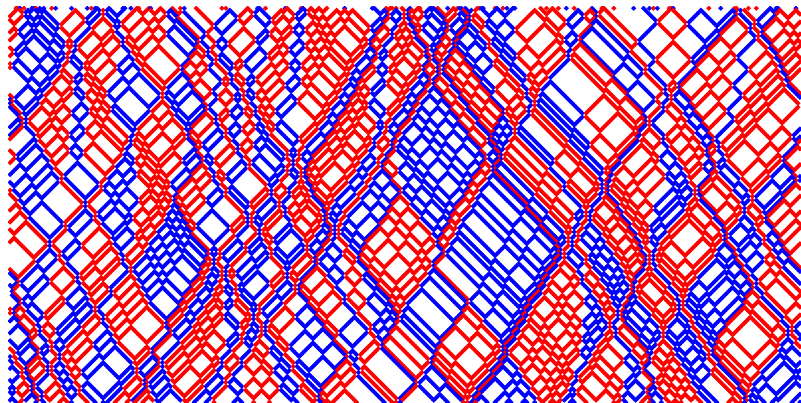
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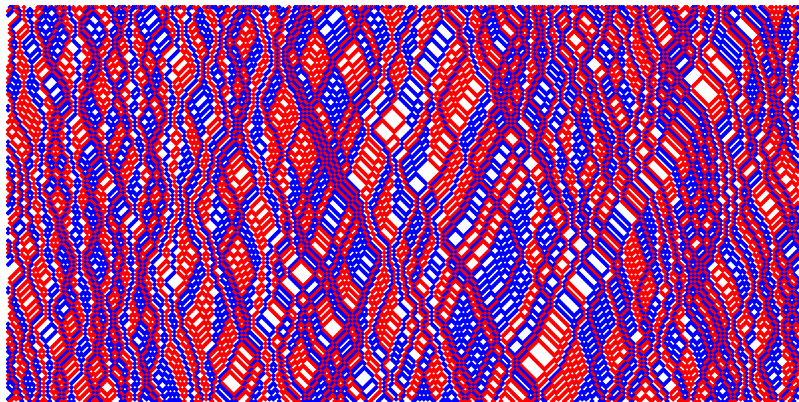
Two color version (low density):



Two color version (medium density):



Two color version (high density):

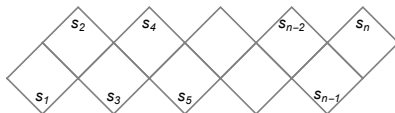


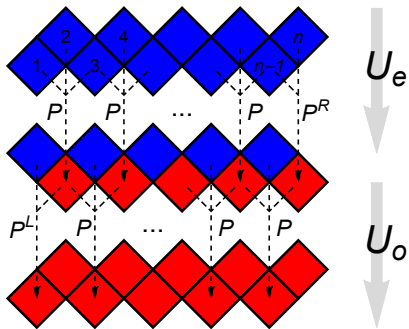
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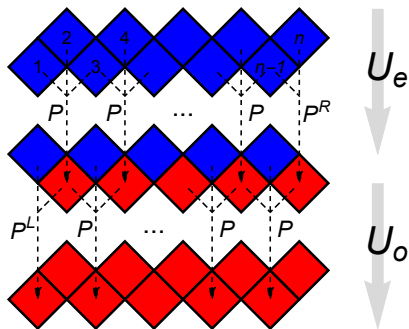
Describe an evolution of *probability state vector* for n -cell automaton

$$\mathbf{p}(t) = U^t \mathbf{p}(0)$$

$$\mathbf{p} = (p_0, p_1, \dots, p_{2^n-1}) \equiv (p_{s_1, s_2, \dots, s_n}; s_j \in \{0, 1\})$$





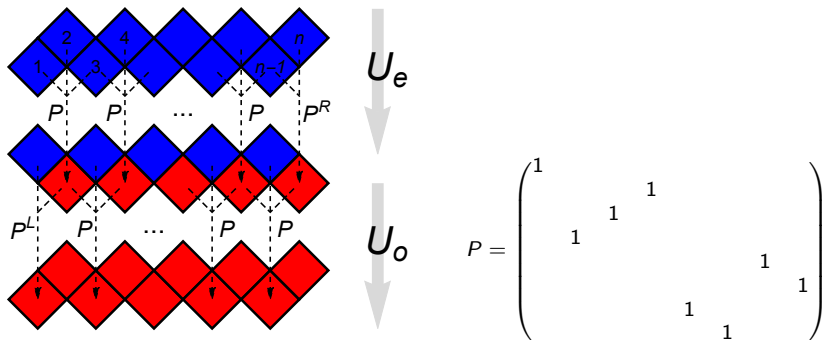


$$U = U_o U_e,$$

$$U_e = P_{123} P_{345} \cdots P_{n-3, n-2, n-1} P_{n-1, n}^R,$$

$$U_o = P_{n-2, n-1, n} \cdots P_{456} P_{234} P_{12}^L.$$



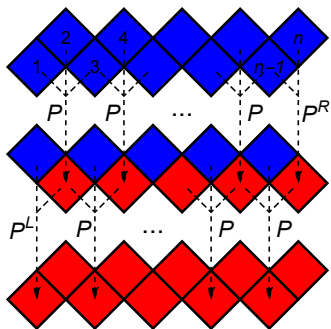


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$$P = \begin{pmatrix} 1 & & & & \\ & 1 & & & \\ & & 1 & & \\ & & & & 1 & \\ & & & & & & 1 \\ & & & & & & & 1 \end{pmatrix}$$

$$P^L = \begin{pmatrix} \alpha & 0 & \alpha & 0 \\ 0 & \beta & 0 & \beta \\ 1-\alpha & 0 & 1-\alpha & 0 \\ 0 & 1-\beta & 0 & 1-\beta \end{pmatrix}$$

$$P^R = \begin{pmatrix} \gamma & \gamma & 0 & 0 \\ 1-\gamma & 1-\gamma & 0 & 0 \\ 0 & 0 & \delta & \delta \\ 0 & 0 & 1-\delta & 1-\delta \end{pmatrix}$$

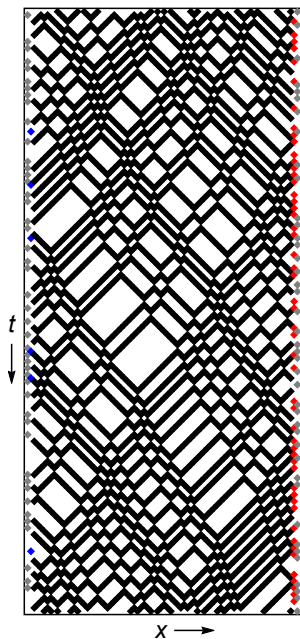
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Some Monte-Carlo to warm up...



Theorem

The $2^n \times 2^n$ matrix U is irreducible and aperiodic for generic values of driving parameters, more precisely, for an open set $0 < \alpha, \beta, \gamma, \delta < 1$.



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Consequence (via *Perron-Frobenius* theorem):
Nonequilibrium steady state (NESS), i.e. fixed point of U

$$U\mathbf{p} = \mathbf{p}$$

is *unique*, and any initial probability state vector is asymptotically (in t) relaxing to \mathbf{p} .



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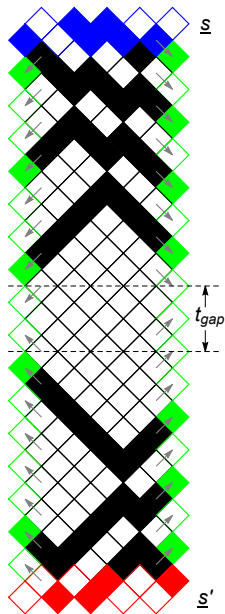
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Idea of the proof:

Show that for any pair of configurations \mathbf{s}, \mathbf{s}' , such t_0 exists that

$$(U^t)_{\mathbf{s}, \mathbf{s}'} > 0, \quad \forall t \geq t_0.$$



[TP and B. Buča, JPA **50**, 395002 (2017)]



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Consider a pair of matrices:

$$W_0 = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ \xi & \xi & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad W_1 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & \xi & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & \omega \end{pmatrix}, \quad \mathbf{W} = \begin{pmatrix} W_0 \\ W_1 \end{pmatrix}$$

and $W'_s(\xi, \omega) := W_s(\omega, \xi)$.



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and $W'_s(\xi, \omega) := W_s(\omega, \xi)$. These satisfy a remarkable **bulk relation**:

$$P_{123} \mathbf{W}_1 S \mathbf{W}_2 \mathbf{W}'_3 = \mathbf{W}_1 \mathbf{W}'_2 \mathbf{W}_3 S$$

or component-wise

$$W_s S W_{\chi(ss's'')} W'_{s''} = W_s W'_{s'} W_{s''} S.$$

where S is a “delimiter” matrix

$$S = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}.$$



Suppose there exists pairs and quadruples of vectors $\langle l_s |$, $\langle l'_{ss'} |$, $|r_{ss'}\rangle$, $|r'_s\rangle$, and a scalar parameter λ , satisfying the following *boundary equations*

$$\begin{aligned}
 P_{123} \langle l_1 | \mathbf{W}_2 \mathbf{W}'_3 &= \langle l'_{12} | \mathbf{W}_3 S, \\
 P_{12}^R |r_{12}\rangle &= \mathbf{W}'_1 S |r'_2\rangle, \\
 P_{123} \mathbf{W}'_1 \mathbf{W}_2 |r'_3\rangle &= \lambda \mathbf{W}'_1 S |r_{23}\rangle, \\
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Suppose there exists pairs and quadruples of vectors $\langle I_s |$, $\langle I'_{ss'} |$, $|r_{ss'}\rangle$, $|r'_s\rangle$, and a scalar parameter λ , satisfying the following *boundary equations*

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Then, the following probability vectors

$$\begin{aligned} \mathbf{p} &\equiv \mathbf{p}_{12\dots n} = \langle I_1 | \mathbf{W}_2 \mathbf{W}'_3 \mathbf{W}_4 \cdots \mathbf{W}'_{n-3} \mathbf{W}_{n-2} | \mathbf{r}_{n-1,n} \rangle, \\ \mathbf{p}' &\equiv \mathbf{p}'_{12\dots n} = \langle I'_{12} | \mathbf{W}_3 \mathbf{W}'_4 \cdots \mathbf{W}_{n-3} \mathbf{W}'_{n-2} \mathbf{W}_{n-1} | \mathbf{r}'_n \rangle, \end{aligned}$$

satisfy the NESS fixed point condition

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Proof: Observe the bulk relations

$$\begin{aligned} P_{123} \mathbf{W}_1 S \mathbf{W}_2 \mathbf{W}'_3 &= \mathbf{W}_1 \mathbf{W}'_2 \mathbf{W}_3 S, \\ P_{123} \mathbf{W}'_1 \mathbf{W}_2 \mathbf{W}'_3 S &= \mathbf{W}'_1 S \mathbf{W}'_2 \mathbf{W}_3 \end{aligned}$$

to move the delimiter S around, when it 'hits' the boundary observe one of the boundary equations. After the full cycle, you obtain $U_o U_e \mathbf{p} = \lambda \lambda^{-1} \mathbf{p}$.



This yields a consistent system of equations which uniquely determine the unknown parameters, namely for the **left** boundary:

$$\xi = \frac{(\alpha + \beta - 1) - \lambda^{-1}\beta}{\lambda^{-2}(\beta - 1)}, \quad \omega = \frac{\lambda^{-1}(\alpha - \lambda^{-1})}{\beta - 1},$$

and for the **right** boundary:

$$\xi = \frac{\lambda(\gamma - \lambda)}{\delta - 1}, \quad \omega = \frac{\gamma + \delta - 1 - \lambda\delta}{\lambda^2(\delta - 1)},$$

yielding

$$\xi = \frac{(\gamma(\alpha + \beta - 1) - \beta)(\beta(\gamma + \delta - 1) - \gamma)}{(\alpha - \delta(\alpha + \beta - 1))^2},$$
$$\omega = \frac{(\delta(\alpha + \beta - 1) - \alpha)(\alpha(\gamma + \delta - 1) - \delta)}{(\gamma - \beta(\gamma + \delta - 1))^2},$$

and explicit expressions for the boundary vectors..



Can we **diagonalize** U with a similar ansatz?



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Yes, a good deal of decay modes can be written as a compact MPA with explicitly positionally dependent matrices

$$\mathbf{W}^{(x)}, \quad \mathbf{W}'^{(x)}$$

depending on $x \in \{2, 3, \dots, n-1\}$ via multiplicative momentum variable z , containing linear combinations of

$$\{1, z^x, z^{-x}\}$$



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For example:

$$\mathbf{W}^{(x)} = (\mathbf{e}_{11} \otimes \mathbf{W}(\xi z, \omega/z) + \mathbf{e}_{22} \otimes \mathbf{W}(\xi/z, \omega z)) \left(\mathbb{1}_8 + \mathbf{e}_{12} \otimes \frac{c_+ z^x F_+ + c_- z^{-x} F_-}{\xi \omega - 1} \right)$$

$$F_+ = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & z \\ 0 & 0 & \frac{\xi \omega - 1}{\omega z^2} & 0 \\ 0 & 0 & 0 & \xi z^2 \end{pmatrix}, \quad F_- = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{\xi^2 z^3} \\ 0 & 0 & \frac{\xi \omega - 1}{\xi z^2} & 0 \\ 0 & 0 & 0 & \omega + \frac{1}{\xi} \left(\frac{1}{z^2} - 1 \right) \end{pmatrix}.$$

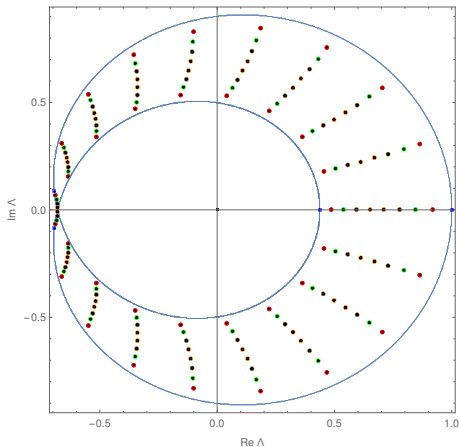


$$U_e \mathbf{p}(z) = \Lambda_L \mathbf{p}'(z), \quad U_o \mathbf{p}'(z) = \Lambda_R \mathbf{p}(z).$$

$$\frac{z(\alpha + \beta - 1) - \beta \Lambda_L}{(\beta - 1) \Lambda_L^2} = \frac{\Lambda_R(\gamma z - \Lambda_R)}{(\delta - 1)z},$$

$$\frac{z(\gamma + \delta - 1) - \delta \Lambda_R}{(\delta - 1) \Lambda_R^2} = \frac{\Lambda_L(\alpha z - \Lambda_L)}{(\beta - 1)z},$$

$$z^{2n-6-4p} = \frac{(\alpha + \beta - 1)^p (\gamma + \delta - 1)^p}{\Lambda_L^{4p} \Lambda_R^{4p}}.$$



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Ultralocal basis $\{[0]_x, [1]_x\}$:

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r -local basis centred on site x :

$$[\alpha_1 \alpha_2 \dots \alpha_r]_x \equiv [\alpha_1]_{x - \lfloor \frac{r}{2} \rfloor} [\alpha_2]_{x - \lfloor \frac{r}{2} \rfloor + 1} \dots [\alpha_r]_{x + \lfloor \frac{r-1}{2} \rfloor}.$$



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$$[\alpha]_x(\mathbf{s}) = \delta_{\alpha, s_x}, \quad ([\alpha]_x [\beta]_y)(\mathbf{s}) = [\alpha]_x(\mathbf{s}) [\beta]_y(\mathbf{s}), \quad \alpha, \beta \in \{0, 1\}, \mathbf{s} \in \{0, 1\}^{\mathbb{Z}}$$

r -local basis centred on site x :

$$[\alpha_1 \alpha_2 \dots \alpha_r]_x \equiv [\alpha_1]_{x - \lfloor \frac{r}{2} \rfloor} [\alpha_2]_{x - \lfloor \frac{r}{2} \rfloor + 1} \dots [\alpha_r]_{x + \lfloor \frac{r-1}{2} \rfloor}.$$

Using unit element $\mathbb{1} = [0]_x + [1]_x$, we can extend the support of each r -local basis element as

$$\begin{aligned} [\alpha_1 \alpha_2 \dots \alpha_r]_x &\equiv \mathbb{1}_{x - \lfloor \frac{r+2}{2} \rfloor} \cdot [\alpha_1 \alpha_2 \dots \alpha_r]_x \cdot \mathbb{1}_{x + \lfloor \frac{r+1}{2} \rfloor} \equiv \\ &\equiv [0 \alpha_1 \alpha_2 \dots \alpha_r 0]_x + [0 \alpha_1 \alpha_2 \dots \alpha_r 1]_x + [1 \alpha_1 \alpha_2 \dots \alpha_r 0]_x + [1 \alpha_1 \alpha_2 \dots \alpha_r 1]_x. \end{aligned}$$



Separable (strongly clustering) states ρ defined by expectation values $\rho(x)$ of ultralocal observables

$$\langle [\alpha_1 \alpha_2 \dots \alpha_r]_x \rangle_\rho = \rho_{x - \lfloor \frac{r}{2} \rfloor}(\alpha_1) \cdot \rho_{x - \lfloor \frac{r}{2} \rfloor + 1}(\alpha_2) \cdots \rho_{x + \lfloor \frac{r-1}{2} \rfloor}(\alpha_r).$$



Separable (strongly clustering) states p defined by expectation values $p(x)$ of ultralocal observables

$$\langle [\alpha_1 \alpha_2 \dots \alpha_r]_x \rangle_p = p_{x - \lfloor \frac{r}{2} \rfloor}(\alpha_1) \cdot p_{x - \lfloor \frac{r}{2} \rfloor + 1}(\alpha_2) \cdots p_{x + \lfloor \frac{r-1}{2} \rfloor}(\alpha_r).$$

Two examples of separable states that we consider:

- 1 A *maximum entropy state*

$$p_x(0) = p_x(1) = 1/2, \quad \forall x \in \mathbb{Z}.$$

- 2 An *inhomogeneous initial state*

$$\begin{cases} p_x(0) = p_x(1) = 1/2, & \text{for } x \leq 0 \\ p_x(0) = 1, \quad p_x(1) = 0. & \text{for } x > 0 \end{cases}$$



$$a^t(\mathbf{s}^0) = a(\mathbf{s}^t)$$



$$a^t(\mathbf{s}^0) = a(\mathbf{s}^t)$$

For 3-site observables, dynamical automorphism is defined as

$$U_x[\alpha \beta \gamma]_y = \begin{cases} [\alpha \chi(\alpha, \beta, \gamma) \gamma]_y; & x = y, \\ [\alpha \beta \gamma]_y; & |x - y| \geq 2, \end{cases}$$

while for any r -local observable it is defined as
a *t-staggered linear homomorphism*

$$a^{t+1} = U(t)a^t$$

$$U(t) = \begin{cases} \prod_{x \in 2\mathbb{Z}} U_x; & t \equiv 0 \pmod{2}, \\ \prod_{x \in 2\mathbb{Z}+1} U_x; & t \equiv 1 \pmod{2}. \end{cases}$$



Theorem (Klobas *et al.* 18): Time evolution of a local observable $[1]_x$ reads

$$[1]_x^t = \sum_{s_{-t}, \dots, s_t \in \{0,1\}} c_{s_{-t}, \dots, s_t}(t) [s_{-t} s_{-t+1} \cdots s_t]_x,$$

where the amplitudes $c_{s_{-t}, \dots, s_t}(t) \in \{0, 1\}$ can be represented as MPA

$$c_{s_{-t}, \dots, s_t}(t) = \langle l(t) | V_{s_{-t}} W_{s_{-t+1}} V_{s_{-t+2}} \cdots W_{s_{t-1}} V_{s_t} | r \rangle + \langle l' | V'_{s_{-t}} W'_{s_{-t+1}} V'_{s_{-t+2}} \cdots W'_{s_{t-1}} V'_{s_t} | r'(t) \rangle.$$

$V_s, W_s, V'_s, W'_s \in \text{End}(\mathcal{V})$, $s \in \{0, 1\}$, are linear operators over auxiliary Hilbert space $\mathcal{V} = \text{lsp}\{|c, w, n, a\rangle$; $c, w \in \mathbb{N}_0$, $n \in \{0, 1, 2\}$, $a \in \{0, 1\}\}$, and can be explicitly expressed in terms of ladder operators and projectors

$$\mathbf{c}^+ = \sum_{c, w, n, a} |c+1, w, n, a\rangle \langle c, w, n, a|, \quad \mathbf{c}^- = (\mathbf{c}^+)^T,$$

$$\mathbf{w}^+ = \sum_{c, w, n, a} |c, w+1, n, a\rangle \langle c, w, n, a|, \quad \mathbf{w}^- = (\mathbf{w}^+)^T,$$

$$\mathbf{e}_{c_2 w_2 n_2 a_2, c_1 w_1 n_1 a_1} = |c_2, w_2, n_2, a_2\rangle \langle c_1, w_1, n_1, a_1|,$$

$$\mathbf{e}_{n_2 a_2, n_1 a_1} = \sum_{c, w} |c, w, n_2, a_2\rangle \langle c, w, n_1, a_1|,$$



$$V_0 = \mathbf{e}_{00,00} + \mathbf{e}_{10,00} + \mathbf{e}_{20,00} + \mathbf{c}^+ \mathbf{e}_{10,01} + \mathbf{e}_{01,01} + \mathbf{c}^+ \mathbf{w}^+ \mathbf{e}_{11,01} + \mathbf{e}_{21,01} + \\ + \mathbf{e}_{0001,0001} + \mathbf{e}_{0011,0001} + \mathbf{e}_{0021,0001},$$

$$V_1 = \mathbf{e}_{00,10} + \mathbf{e}_{10,20} + \mathbf{e}_{20,20} + \mathbf{e}_{00,11} + \mathbf{e}_{10,21} + \mathbf{e}_{20,21} + \mathbf{e}_{01,11} + \\ + \mathbf{w}^+ \mathbf{e}_{11,21} + \mathbf{w}^+ \mathbf{e}_{21,21} + \mathbf{e}_{0001,0011} + \mathbf{e}_{0011,0021} + \mathbf{e}_{0021,0021},$$

$$W_0 = \mathbf{c}^- \mathbf{w}^+ (\mathbf{e}_{00,00} + \mathbf{e}_{10,00} + \mathbf{e}_{20,00}) + \mathbf{w}^+ \mathbf{e}_{10,01} + \mathbf{w}^+ \mathbf{e}_{01,01} + \\ + \mathbf{c}^+ (\mathbf{w}^+)^2 \mathbf{e}_{11,01} + \mathbf{w}^+ \mathbf{e}_{21,01} + \mathbf{e}_{1111,0001} + \mathbf{e}_{0001,0001} + \mathbf{e}_{0011,0001} + \mathbf{e}_{0021,0001},$$

$$W_1 = \mathbf{c}^- \mathbf{w}^+ (\mathbf{e}_{00,10} + \mathbf{e}_{10,20} + \mathbf{e}_{20,20}) + \mathbf{w}^+ \mathbf{e}_{01,11} + \mathbf{c}^+ \mathbf{w}^+ \mathbf{e}_{11,21} + \\ + \mathbf{c}^+ \mathbf{w}^+ \mathbf{e}_{21,21} + \mathbf{e}_{0001,0011} + \mathbf{e}_{0011,0021} + \mathbf{e}_{0021,0021},$$

$$V'_0 = V_0^T - (\mathbf{e}_{0001,1111} + \mathbf{e}_{0101,1211} + \mathbf{e}_{0101,1110}),$$

$$V'_1 = V_1^T,$$

$$W'_0 = W_0^T - (\mathbf{e}_{0001,1111} + \mathbf{e}_{0000,1211}),$$

$$W'_1 = W_1^T - (\mathbf{e}_{0021,1111} + \mathbf{e}_{0021,1121} + \mathbf{e}_{0121,1211} + \mathbf{e}_{0121,1221}).$$



$$V_0 = \mathbf{e}_{00,00} + \mathbf{e}_{10,00} + \mathbf{e}_{20,00} + \mathbf{c}^+ \mathbf{e}_{10,01} + \mathbf{e}_{01,01} + \mathbf{c}^+ \mathbf{w}^+ \mathbf{e}_{11,01} + \mathbf{e}_{21,01} + \\ + \mathbf{e}_{0001,0001} + \mathbf{e}_{0011,0001} + \mathbf{e}_{0021,0001},$$

$$V_1 = \mathbf{e}_{00,10} + \mathbf{e}_{10,20} + \mathbf{e}_{20,20} + \mathbf{e}_{00,11} + \mathbf{e}_{10,21} + \mathbf{e}_{20,21} + \mathbf{e}_{01,11} + \\ + \mathbf{w}^+ \mathbf{e}_{11,21} + \mathbf{w}^+ \mathbf{e}_{21,21} + \mathbf{e}_{0001,0011} + \mathbf{e}_{0011,0021} + \mathbf{e}_{0021,0021},$$

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$$V'_0 = V_0^T - (\mathbf{e}_{0001,1111} + \mathbf{e}_{0101,1211} + \mathbf{e}_{0101,1110}),$$

$$V'_1 = V_1^T,$$

$$W'_0 = W_0^T - (\mathbf{e}_{0001,1111} + \mathbf{e}_{0000,1211}),$$

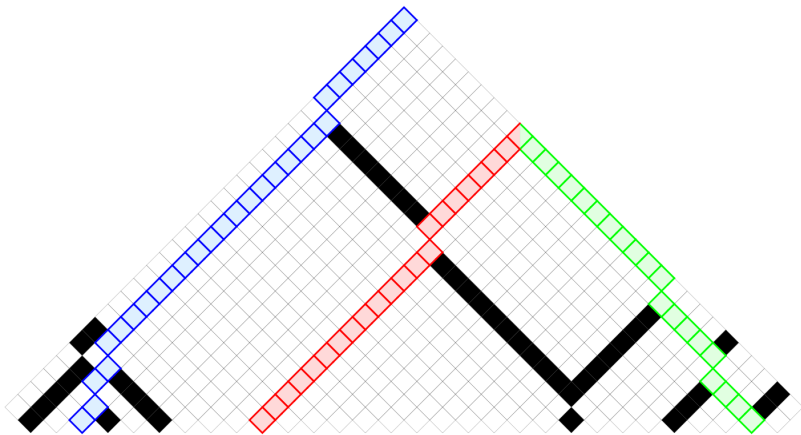
$$W'_1 = W_1^T - (\mathbf{e}_{0021,1111} + \mathbf{e}_{0021,1121} + \mathbf{e}_{0121,1211} + \mathbf{e}_{0121,1221}).$$

The time-dependent auxiliary space boundary vectors take the following form:

$$\begin{aligned} \langle l(t) | &= \langle 0, t, 0, 0 |, \\ |r\rangle &= |0, 0, 0, 0\rangle + |0, 0, 0, 1\rangle + |0, 0, 0, 2\rangle, \\ \langle l' | &= \langle 0, 0, 0, 1 | + \langle 0, 0, 1, 1 | + \langle 0, 0, 2, 1 | + \langle 0, 1, 0, 1 | + \langle 0, 1, 2, 1 |, \\ |r'(t)\rangle &= |0, t + 1, 0, 0\rangle. \end{aligned} \tag{1}$$



Proof: 'Real space, real time inverse scattering transform'



The weight of left MPA $\langle I(t) | V_{s-t} W_{s-t+1} V_{s-t+2} \cdots W_{s_t-1} V_{s_t} | r \rangle$ is 1 (or 0) if the configuration $(s_{-t}, s_{-t+1}, \dots, s_t)$ can (cannot) be obtained in a light-cone with the left-mover at the origin!



$$C(x, t) = \langle [1]_x [1]_0^t \rangle_P - \langle [1]_x \rangle_P \langle [1]_0^t \rangle_P = \langle [1]_x [1]_0^t \rangle_P - \frac{1}{4}$$



$$C(x, t) = \langle [1]_x [1]_0^t \rangle_P - \langle [1]_x \rangle_P \langle [1]_0^t \rangle_P = \langle [1]_x [1]_0^t \rangle_P - \frac{1}{4}$$

Using time-dependent MPA:

$$C(x, t) = \frac{1}{2^{2t+1}} \left(\langle l(t) | T^{\frac{x+t}{2}} V_1 \bar{T}^{t-\frac{x+t}{2}} | r \rangle + \langle l' | \bar{T}'^{\frac{x+t}{2}} V_1' T'^{t-\frac{x+t}{2}} | r'(t) \rangle \right) - \frac{1}{4}$$

with

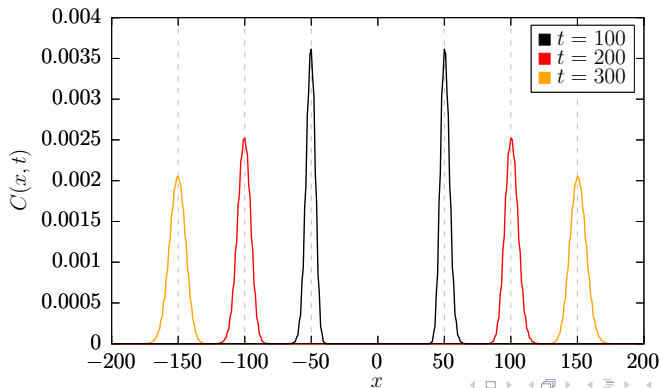
$$\begin{aligned} T &= (V_0 + V_1)(W_0 + W_1), & \bar{T} &= (W_0 + W_1)(V_0 + V_1), \\ T' &= (W'_0 + W'_1)(V'_0 + V'_1), & \bar{T}' &= (V'_0 + V'_1)(W'_0 + W'_1). \end{aligned}$$



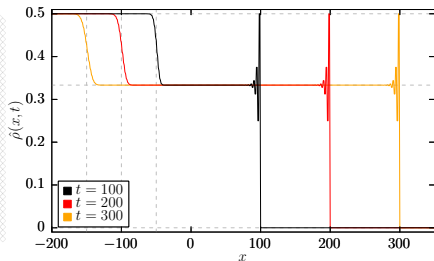
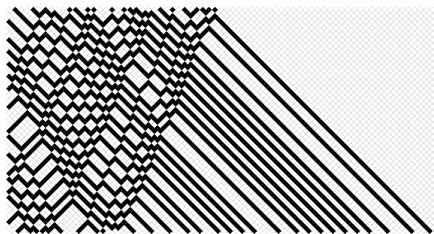
We find normal hydrodynamic scaling!

For maximum entropy ('infinite temperature') state, tMPA yields

$$C(x, t) = 2^{-t-1} \sum_{m=0}^{\frac{t-|x|-2}{2}} 4^m \left(2 \binom{t-2m-3}{m} - \binom{t-2m-2}{m} \right)$$
$$\approx \frac{1}{16\sqrt{t\pi}} \exp\left(-\frac{4}{t} \left(|x| - \frac{t}{2}\right)^2\right).$$



Exact solution of inhomogeneous quench problem



$$\hat{\rho}(x, t) = \langle [1]_x \rangle_{p_{\text{inhom}}^t} = \langle [1]_x^{-t} \rangle_{p_{\text{inhom}}}$$

Exact solution exhibits the following simple asymptotic behavior:

- Quasi-free regime

$$\hat{\rho}\left(t \geq x \geq -\frac{t}{3} + 1, t\right) = \frac{1}{3} \left(1 - \left(-\frac{1}{2}\right)^{\lfloor \frac{t-x+1}{2} \rfloor} \right)$$

- Thermalizing (diffusive) regime

$$\lim_{t \rightarrow \infty} \hat{\rho}\left(-\frac{t}{2} + \zeta\sqrt{t}, t\right) = \frac{1}{12} (5 - \text{erf}(2\zeta))$$



[B.Buča, J.P.Garrahan, T.Prosen, M.Vanicat, arXiv:1901.00845]
Large deviation theory for arbitrary observable of the form:

$$\mathcal{O}_T = \sum_{t=0}^{T-1} \sum_{x=1}^{N-1} \left[f_x(s_x^t, s_{x+1}^t) + g_x(s_x^{t+1/2}, s_{x+1}^{t+1/2}) \right]$$



[B.Buča, J.P.Garrahan, T.Prosen, M.Vanicat, arXiv:1901.00845]

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Tilted Markov generator:

$$\tilde{U}(s) = U_o G(s) U_e F(s).$$

$$F(s) = F_{12}^{(1)} F_{23}^{(2)} F_{34}^{(3)} \dots F_{N-1,N}^{(N-1)} \quad \text{and} \quad G(s) = G_{12}^{(1)} G_{23}^{(2)} G_{34}^{(3)} \dots G_{N-1,N}^{(N-1)}$$

where

$$F^{(x)} = \begin{pmatrix} f_{0,0}^{(x)} & 0 & 0 & 0 \\ 0 & f_{0,1}^{(x)} & 0 & 0 \\ 0 & 0 & f_{1,0}^{(x)} & 0 \\ 0 & 0 & 0 & f_{1,1}^{(x)} \end{pmatrix}, \quad f_{s,s'}^{(x)} \equiv e^{sf_x(s,s')}$$

and similar for $G^{(x)}$.



There exist 3×3 matrices satisfying bulk algebraic conditions:

$$f_{ss'}^{(j-1)} f_{s's''}^{(j)} W_s^{(j-1)} W_{s'}^{(j)} X_{s''}^{(j+1)} = X_s^{(j-1)} V_{\chi(ss's'')}^{(j)} V_{s''}^{(j+1)},$$
$$g_{ss'}^{(j-2)} g_{s's''}^{(j-1)} X_s^{(j-2)} V_{s'}^{(j-1)} V_{s''}^{(j)} = W_s^{(j-2)} W_{\chi(ss's'')}^{(j-1)} X_{s''}^{(j)},$$



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and boundary equations

$$f_{ss'}^{(1)} f_{s's''}^{(2)} \langle l_s | W_{s'}^{(2)} X_{s''}^{(3)} = \langle l'_{s\chi(ss's'')} | V_{s''}^{(3)},$$

$$\sum_{m,m'=0,1} R_{ss'}^{mm'} f_{mm'}^{(N-1)} |r_{mm'}\rangle = \lambda_R X_s^{(N-1)} |r'_{s'}\rangle,$$

$$\sum_{m,m'=0,1} L_{ss'}^{mm'} g_{mm'}^{(1)} \langle l'_{mm'} | = \lambda_L \langle l_s | X_{s'}^{(2)},$$

$$g_{ss'}^{(N-2)} g_{s's''}^{(N-1)} X_s^{(N-2)} V_{s'}^{(N-1)} |r'_{s''}\rangle = W_s^{(N-2)} |r_{\chi(ss's'')s''}\rangle,$$



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$$f_{ss'}^{(j-1)} f_{s's''}^{(j)} W_s^{(j-1)} W_{s'}^{(j)} X_{s''}^{(j+1)} = X_s^{(j-1)} V_{\chi(ss's'')}^{(j)} V_{s''}^{(j+1)},$$

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$$\sum_{m,m'=0,1} R_{ss'}^{mm'} f_{mm'}^{(N-1)} |r_{mm'}\rangle = \lambda_R X_s^{(N-1)} |r'_{s'}\rangle,$$

$$\sum_{m,m'=0,1} L_{ss'}^{mm'} g_{mm'}^{(1)} \langle l'_{mm'} | = \lambda_L \langle l_s | X_{s'}^{(2)},$$

$$g_{ss'}^{(N-2)} g_{s's''}^{(N-1)} X_s^{(N-2)} V_{s'}^{(N-1)} |r'_{s''}\rangle = W_s^{(N-2)} |r_{\chi(ss's'')s''}\rangle,$$

such that MPA:

$$p_{s_1, \dots, s_N} = \langle l_{s_1} | W_{s_2}^{(2)} W_{s_3}^{(3)} \dots W_{s_{N-3}}^{(N-3)} W_{s_{N-2}}^{(N-2)} |r_{s_{N-1}s_N}\rangle$$

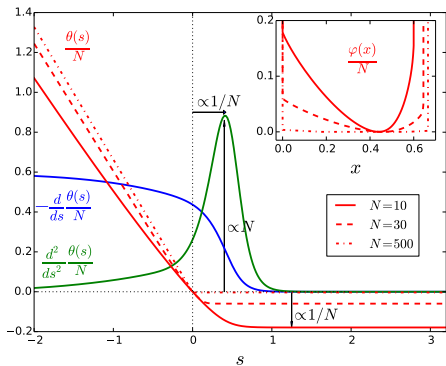
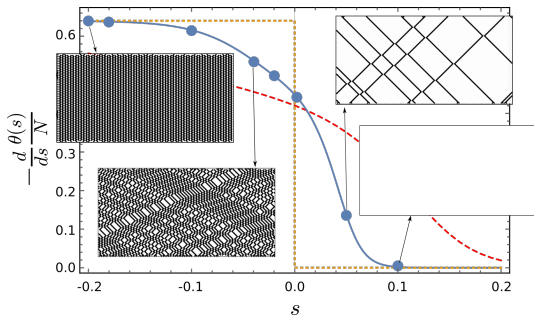
$$p'_{s_1, \dots, s_N} = \langle l'_{s_1 s_2} | V_{s_3}^{(3)} V_{s_4}^{(4)} \dots V_{s_{N-2}}^{(N-2)} V_{s_{N-1}}^{(N-1)} |r'_{s_N}\rangle,$$

solves the eigenvalue equation

$$\tilde{U}(s)\mathbf{p} = \Lambda(s)\mathbf{p}$$

and $\Lambda(s) = e^{\theta(s)}$ is a root of third order polynomial.





- Interacting integrable model about which we can compute everything: *quenches, non-equilibrium steady states with baths, relaxation rates, dynamical structure factor, large deviations etc.*
- Generalizations (stochastic/unitary branching)?
Link to Yang-Baxter integrability missing?
- Testbed for computing diffusive corrections to generalized hydrodynamics.
See e.g.: S. Gopalakrishnan, D. Huse, V. Khemani, R. Vasseur, PRB **98**, 220303 (2018)

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Extra: Reversible-deterministic (symplectic) dynamical map over $(\mathcal{S}^2)^{\times N}$

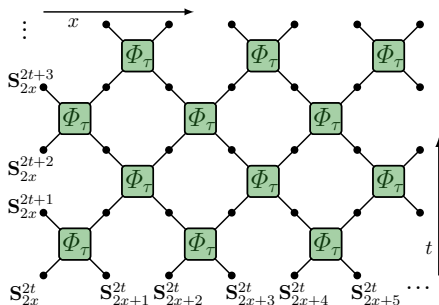
Family of rational-symplectic maps over $\mathcal{S}^2 \times \mathcal{S}^2$ ($\mathbf{S}_1 \cdot \mathbf{S}_1 = \mathbf{S}_2 \cdot \mathbf{S}_2 = 1$):

$$\Phi_\tau(\mathbf{S}_1, \mathbf{S}_2) = \frac{1}{\sigma^2 + \tau^2} \left(\sigma^2 \mathbf{S}_1 + \tau^2 \mathbf{S}_2 + \tau \mathbf{S}_1 \times \mathbf{S}_2, \sigma^2 \mathbf{S}_2 + \tau^2 \mathbf{S}_1 + \tau \mathbf{S}_2 \times \mathbf{S}_1 \right),$$

$$\sigma^2 := \frac{1}{2} \left(1 + \mathbf{S}_1 \cdot \mathbf{S}_2 \right),$$

defining discrete space-time many-body symplectic dynamics
(classical local Floquet circuit)

$$(\mathbf{S}_{2x}^{2t+1}, \mathbf{S}_{2x+1}^{2t+1}) = \Phi_\tau(\mathbf{S}_{2x}^{2t}, \mathbf{S}_{2x+1}^{2t}), \quad (\mathbf{S}_{2x-1}^{2t+2}, \mathbf{S}_{2x}^{2t+2}) = \Phi_\tau(\mathbf{S}_{2x-1}^{2t+1}, \mathbf{S}_{2x}^{2t+1}),$$



Defining \mathbb{I} a identity map over \mathcal{S}^2 we find (note that $\Phi_\infty(\mathbf{S}_1, \mathbf{S}_2) = (\mathbf{S}_2, \mathbf{S}_1)$):

$$\left(\Phi_\lambda \otimes \mathbb{I}\right) \circ \left(\mathbb{I} \otimes \Phi_{\lambda+\mu}\right) \circ \left(\Phi_\mu \otimes \mathbb{I}\right) = \left(\mathbb{I} \otimes \Phi_\mu\right) \circ \left(\Phi_{\lambda+\mu} \otimes \mathbb{I}\right) \circ \left(\mathbb{I} \otimes \Phi_\lambda\right).$$



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Furthermore, defining a matrix valued function $L(\lambda) : \mathcal{S}^2 \rightarrow \text{End}(\mathbb{C}^2)$

$$L(\mathbf{S}; \lambda) = \mathbb{I} + \frac{1}{2i\lambda} \mathbf{S} \cdot \boldsymbol{\sigma},$$

we find that RLL relation is obeyed:

$$L(\mathbf{S}_2; \lambda)L(\mathbf{S}_1; \mu) = L(\mathbf{S}'_2; \mu)L(\mathbf{S}'_1; \lambda), \quad (\mathbf{S}'_1, \mathbf{S}'_2) := \Phi_{\lambda-\mu}(\mathbf{S}_1, \mathbf{S}_2).$$



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$$\left(\Phi_\lambda \otimes \mathbb{I}\right) \circ \left(\mathbb{I} \otimes \Phi_{\lambda+\mu}\right) \circ \left(\Phi_\mu \otimes \mathbb{I}\right) = \left(\mathbb{I} \otimes \Phi_\mu\right) \circ \left(\Phi_{\lambda+\mu} \otimes \mathbb{I}\right) \circ \left(\mathbb{I} \otimes \Phi_\lambda\right).$$

Furthermore, defining a matrix valued function $L(\lambda) : \mathcal{S}^2 \rightarrow \text{End}(\mathbb{C}^2)$

$$L(\mathbf{S}; \lambda) = \mathbb{1} + \frac{1}{2i\lambda} \mathbf{S} \cdot \boldsymbol{\sigma},$$

we find that RLL relation is obeyed:

$$L(\mathbf{S}_2; \lambda)L(\mathbf{S}_1; \mu) = L(\mathbf{S}'_2; \mu)L(\mathbf{S}'_1; \lambda), \quad (\mathbf{S}'_1, \mathbf{S}'_2) := \Phi_{\lambda-\mu}(\mathbf{S}_1, \mathbf{S}_2).$$

Defining monodromy-matrix

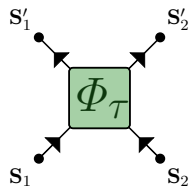
$$T(\mathbf{S}_0, \mathbf{S}_1, \dots, \mathbf{S}_{N-1}; \lambda, \mu) = \text{tr} \left(\overleftarrow{\prod_{x=0}^{N/2-1} L(\mathbf{S}_{2x+1}; \lambda)L(\mathbf{S}_{2x}; \mu)} \right),$$

subsequent application of RLL relations shows manifest conservation of its trace (for any λ while $\mu = \lambda - \tau$)

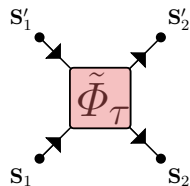
$$T(\mathbf{S}_0^t \dots \mathbf{S}_{N-1}^t; \lambda, \lambda - \tau) = T(\mathbf{S}_0^{t+1} \dots \mathbf{S}_{N-1}^{t+1}; \lambda - \tau, \lambda) = T(\mathbf{S}_0^{t+2} \dots \mathbf{S}_{N-1}^{t+2}; \lambda, \lambda - \tau).$$

$$\begin{aligned} Q_k^{\text{even}} &= \partial_\lambda^k \log |T(\lambda, \lambda - \tau)|^2 \Big|_{\lambda = -\frac{i}{2}}, \\ Q_k^{\text{odd}} &= \partial_\lambda^k \log |T(\lambda, \lambda - \tau)|^2 \Big|_{\lambda = \tau - \frac{i}{2}}, \quad k = 0, 1, 2, \dots \end{aligned}$$



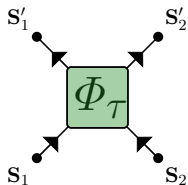


$$(\mathbf{S}'_1, \mathbf{S}'_2) = \Phi_\tau(\mathbf{S}_1, \mathbf{S}_2),$$

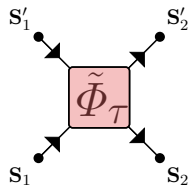


$$(\mathbf{S}_2, \mathbf{S}'_2) = \tilde{\Phi}_\tau(\mathbf{S}_1, \mathbf{S}'_1).$$





$$(\mathbf{S}'_1, \mathbf{S}'_2) = \Phi_\tau(\mathbf{S}_1, \mathbf{S}_2),$$



$$(\mathbf{S}_2, \mathbf{S}'_2) = \tilde{\Phi}_\tau(\mathbf{S}_1, \mathbf{S}'_1).$$

$$\Xi \circ \tilde{\Phi}_\tau = \Phi_\tau \circ (-\Xi),$$

$$\Xi(\mathbf{S}, \mathbf{S}') := (\mathbf{S}, -\mathbf{S}'), \quad (-\Xi)(\mathbf{S}, \mathbf{S}') := (-\mathbf{S}, \mathbf{S}').$$



$$C(x, t) = \langle S_x^t S_0^0 \rangle - \langle S_x^t \rangle \langle S_0^0 \rangle$$

