# Si Micro Pixel Detector

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1. Pixel Detector at RHIC experiment

2. Pixel Detector for RIBF experiment

## RHICでの物理からの要求



荷電粒子総数 ~ 2000 この中から Charm quark bottom quark を見つけ る。



## Feature of Silicon Detector

- High dE/dx (~ 2MeV /(g/cm^2))
  - Solid state detector comparing to gas chamber -> thin detector
- Low e-h pair creation energy
   3.6 eV instead of 13.6 eV for gas chamber
- Available Technology
  - Small and precise
  - Huge number of read out channel
- But no intrinsic amplification
  - Required low noise electronics

## **Required Specification**

- Collision Rate ~ 10MHz -> Timing Resolution < 100nsec
- Trigger Rate 5KHz ~ 10KHz
- Occupancy < 1% for pixel detector</li>
- 50 \* 425 micron • Pixel size
- Tracking Resolution 50micron for displacement
- High precision at mechanical construction ~ 25 micron for internal
- Material Budget ~ 1% of radiation length 荷電粒子の多重散乱、ガンマ線による電子ー陽電子対発 生をふせぐ

### Full detector shape

 Inner 2 barrel will be equipped with silicon Pixel detector





### Current baseline for layer 1&2 position -



### Current pixel ladder baseline -

Current CAD model has sensors in neighboring ladders aligned to their ideal edge location – no allowance for positioning error. Currently RIKEN proposes 10. micron sensor positioning tolerance, HYTEC proposes 25. – 50. microns positioning tolerance ladder to ladder.



## Specification

VTX	Layer	R1		R2	R3	R4
Geometrical dimensions	R (cm)	2.5		5	10	14
	∆z (cm)	21.8		21.8	31.8	38.2
	Area (cm <sup>2</sup> )	280		560	1240	1600
Channel count	Sensor size $R \times z$ (cm <sup>2</sup> )	1.28 × 1.36 (256 × 32 pixels)		$3.43 \times 6.36 \\ (384 \times 2 \text{ strips})$		
	Channel size	$50\times425~\mu m^2$		80 $\mu$ m $\times$ 3 cm (effective 80 $\times$ 1000 $\mu$ m <sup>2</sup> )		
	Sensors/ladder	2 × 8		5	6	
	Ladders	10		20	18	26
	Sensors	160		320	90	144
	Readout chips	160		320	1080	1728
	Readout channels	1,310,720	2	,621,440	138,240	221,184
Radiation length (X/X0)	Sensor	0.2%		0.5 %		
	Readout	0.16%		0.8 %		
	Bus	0.14%				
	Ladder & cooling	0.7%		0.7 %		
	Total	1.2%		2.0 %		

- **ピクセルセンサー**  p-in-n シリコンピクセルセンサー
- 厚さ200µm (最小電離粒子:15000e<sup>-</sup>)
- 32 x 256 (x4) ピクセル
- ピクセルの大きさ
  - 50 x 425µm<sup>2</sup>
  - Intrinsic Resolution = 50 /  $\sqrt{12}$  = 14µm
  - Diffusion + 多重散乱 ~ 10µm
- 有感面積 12.8 x 13.6mm<sup>2</sup>
- 空乏化電圧 ~8V







### 読み出しチップ



### Readout chip probing

**Typical results** 



Class II All functions are OK, but defect pixels > 1%

Class III Not working with function



# **Bump bonding**



Bump bond to silicon pixel sensor





### Pixel detector module

- Sensor module consists of 4 ALICE Pixel readout chips Bump-bonded to silicon sensor
- One readout unit, half stave, made from two sensor modules
- Half stave is mounted on the support structure
- Pixel BUS to bring data out and send control signal in to the readout chip is mounted on the half stave
- Each detector module is built of two half staves, read out on the barrel ends



### **Bus structure**

- 5 layers structure
- GND, Power and 3 signal lines

#### **Final configuration**

Signal-1 3 µm Cu

Signal-2 3 µm Cu

Signal-3 3 µm Cu

#### Power 50 $\mu m$ Al

#### GND 50 µm Al



**Signal 1; (for Surface Mount Device)** Signal-1, Signal-2, and signal-3 are connected with through hole

Signal 2; (Vertical line) line connected with

pixel chip with wire bonding

**Signal 3; (Horizontal line)** send signal to Pilot Module connected with vertical line with through hole

Signal lines; 60 μm pitch Material Budget; Total ~ 0.26 %

## Bus



Using 3 micron thick Cu as signal patterns and 50 micron Al for GND/Power line.

Cu Pattern and through hole are manufactured industry standard technology. ->

# Alignment

•Relative position between jigs is determined by linear bush and pin at  $<5\mu m$ accuracy in order to assemble stave at  $<25\mu$ m precision.

• Jigs have a flexibility for modification of the component.

Linear bush:

structure

Linear ball bearing •Detailed and quantitative procedures to keep good uniformity and reproducibility inside in the shell



corresponded to each sensor

# Gluing

1.Set the jig on the glue dispenser robot
2.Set the C/C support and on the jig
3.Dispense the glue on the support
4.Glue the sensor and support with micrometer to control the thickness of glue
5.Take out the jig

**Dispenser robot** 



by micrometer Sensors have been chucking to fix until glue is cured.

Stopper controlled

Also, assembly procedure for bus is as same as the procedure for sensor.

## Jigs have been delivered on 24 March



## Assembling



1.5cmハーフラダー • 1.5cmハーフラダーが完成した。



# **Pixel Readout Overview**



#### Chain Test at Stony Brook in this week



#### **Pixel Ladder**

#### SPIRO





### 2. Cosmic-ray Experiment



#### Test Results

- DAQ system was operated successfully.
- Clear track of cosmic-ray was detected for 50 events.



# Plan

- Finalized pre-production version of ladder soon
- Start production ladder in late spring/ early summer 2008
- Production ladder finish : fall
- Start to assembly into whole structure : fall
- Install into PHENIX : Summer 2008
- Start experiment with pixel part : Winter 2008

# **RIBF Experiment**

- 大津さんの話とこのWork Shopでの話し
- Rate 10<sup>6</sup> Hz/cm<sup>2</sup>
- Dynamic Range 2500
- Low material  $t/RL = 10^{-4}$

## Rate

- Shaping time ~ 30nsec -> 10MHz / pixel Trigger rate ~ 20KHz
- -> Optimize pixel size 50\*500 μm<sup>2</sup> is too small for rate Larger pixel size -> Easy to develop readout Minimize total number of readout channel

# Dynamic range > 2500

- Current pixel detector is threshold type readout.
- Noise may be small problem at preamp.
   -> Increase noise by detector
   Capacitance ∝ pixel area
- ADC readout ??
  - There are some development on going
  - How much resolution in highest range?

#### 前置増幅器



# Material budget

- Si can be thinner, but manufacture can not handle such thin sliced silicon.
- Readout electronics has some thickness.
- 100-200 μm may be OK.
- But not t/RL ~ 10<sup>-4</sup>

# Summary

- Radiation-lab group has been developed Si pixel sensor for high position resolution MIP detection.
- This can be used for RIBF experiments?
- If you need position resolution and high rate capability, Si pixel /Strip may be best solution.