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Complete control of a gene regulatory network of ascidian embryo by a few factors identified by a mathematical theory

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By the success of modern biology, we have many examples of large networks consisting of many species of bio-molecules and interactions between them. It is believed that the dynamics of molecular activities based on such networks are the origin of biological functions. To understand the dynamics of complex systems, we have developed Linkage Logic theory, by which key molecules (FVS) to control the dynamics of a whole system can be determined from the topology of the regulatory linkages alone. We have applied the theory to a gene regulatory network (GRN) for fate specification of seven tissues (epidermis, brain, nerve cord, endoderm, notochord, mesenchyme, muscle) in ascidian embryos. From the analysis we found that dynamics of the network including more than 90 genes is controllable by manipulation of only 5 genes. We verified our prediction by combinatorial experiments of knockdown and overexpression, and obtained the results that six out of seven tissues except for muscle could be induced by experimental manipulations of these 5 genes. These successful results, at the same time, suggested that the experimentally identified GRN might be incomplete and lack the information responsible for muscle. Then, we analyzed the GRN and updated the network by combining linkage logic and experiments. We listed candidates of missing edges in the GRN under a criterion that adding one of the edges changes the FVS. We found that one of the candidates does exist actually. From an updated version of the GRN, we identified 6 (not 5) key factors. Then, we confirmed that by manipulating the activity of the 6 factors, all of seven cell types were successfully induced. The modelfree approaches based on the linkage logic will promote understanding dynamics of biological systems in life sciences.