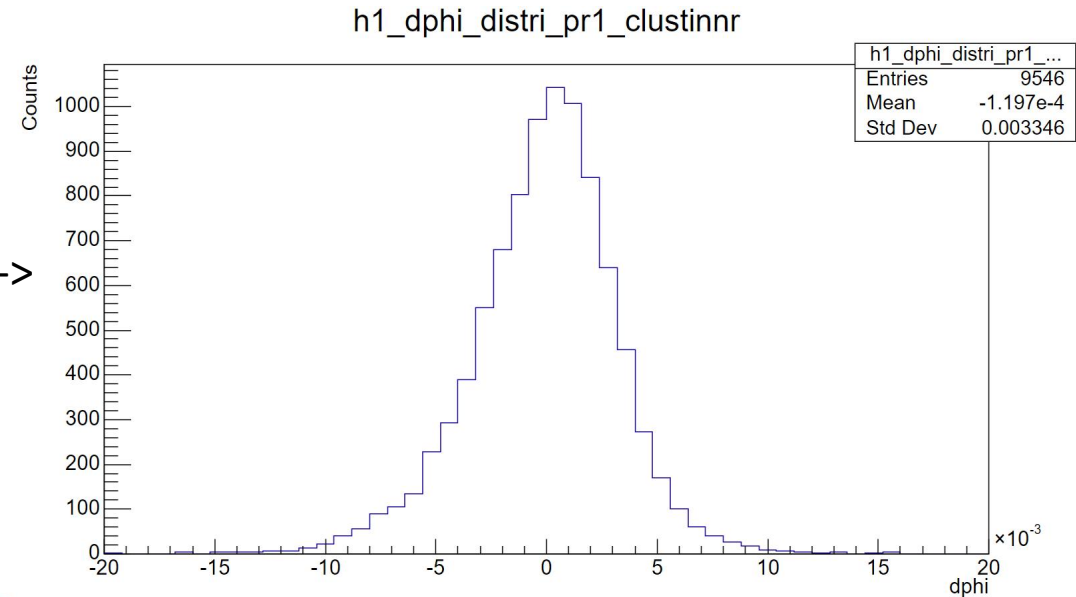
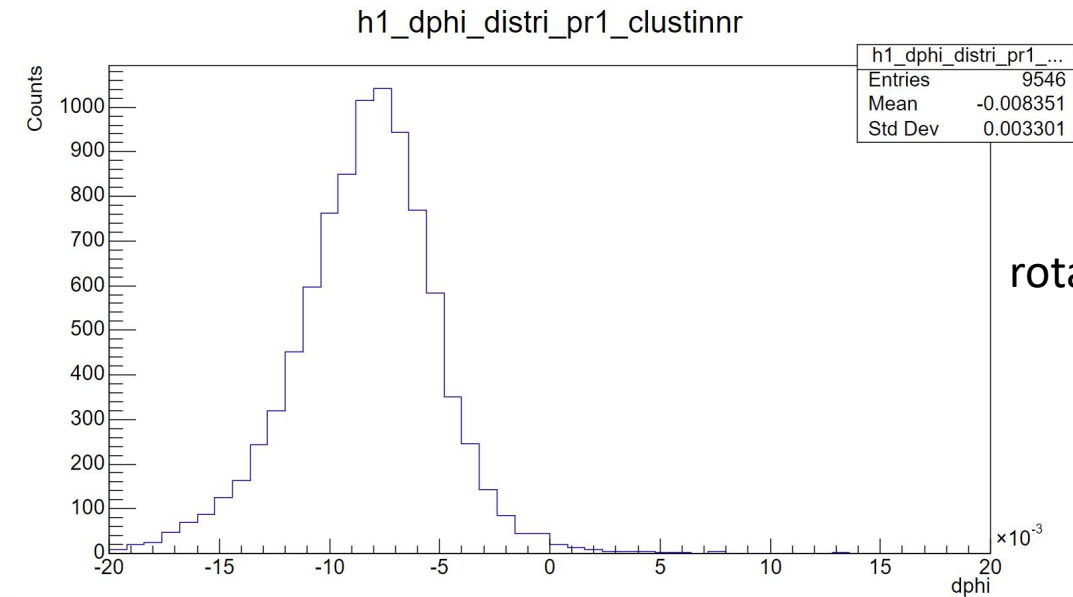


dphi(truth - reco) vs pT

dphi(truth - reco) vs pT

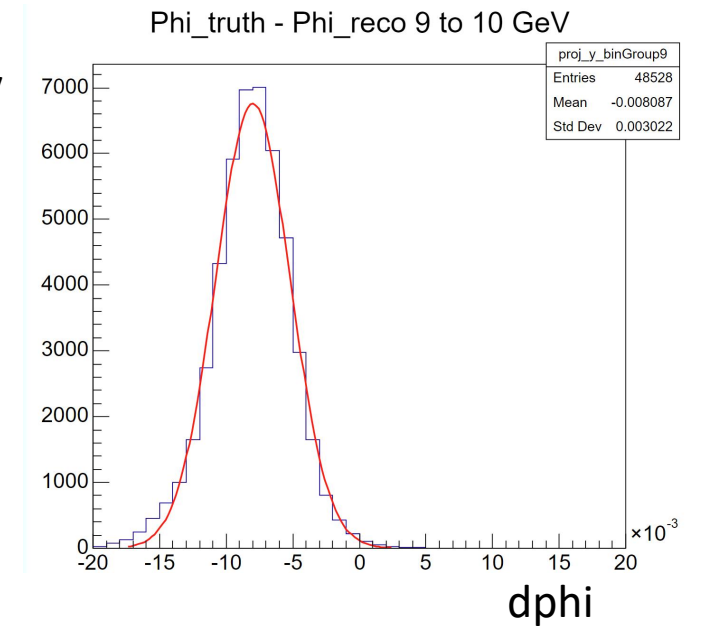
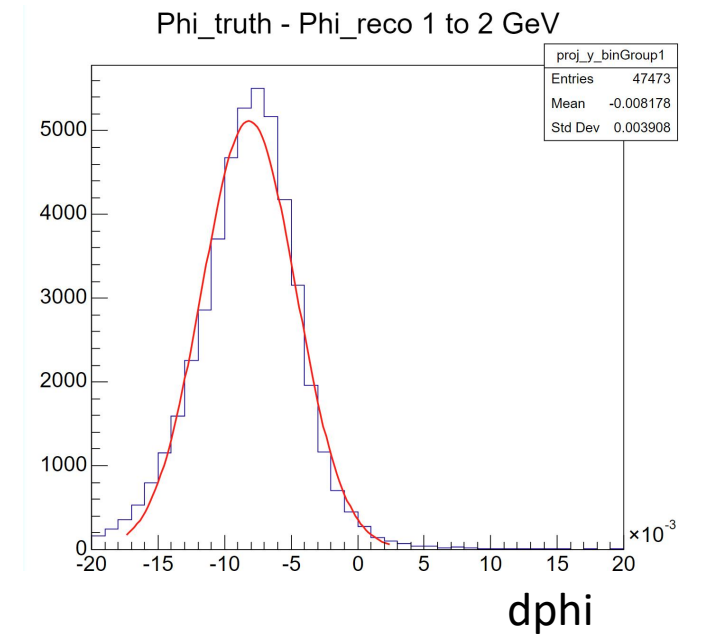
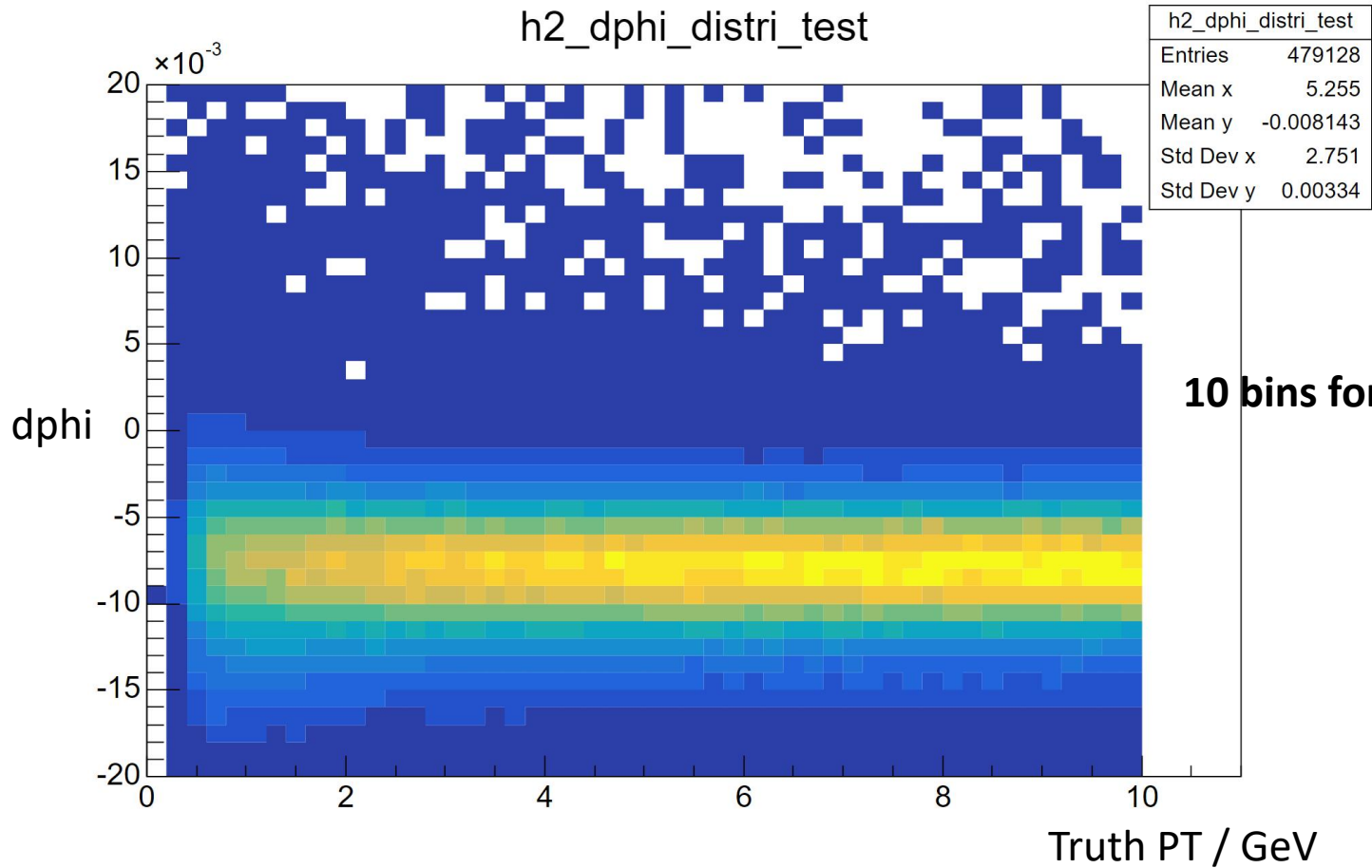
truth_phi: electron hit on emcal surface phi
reco_phi: cluster inner face center phi



For the distributions without any corrections applied, we studied the dphi performance in different pt range.

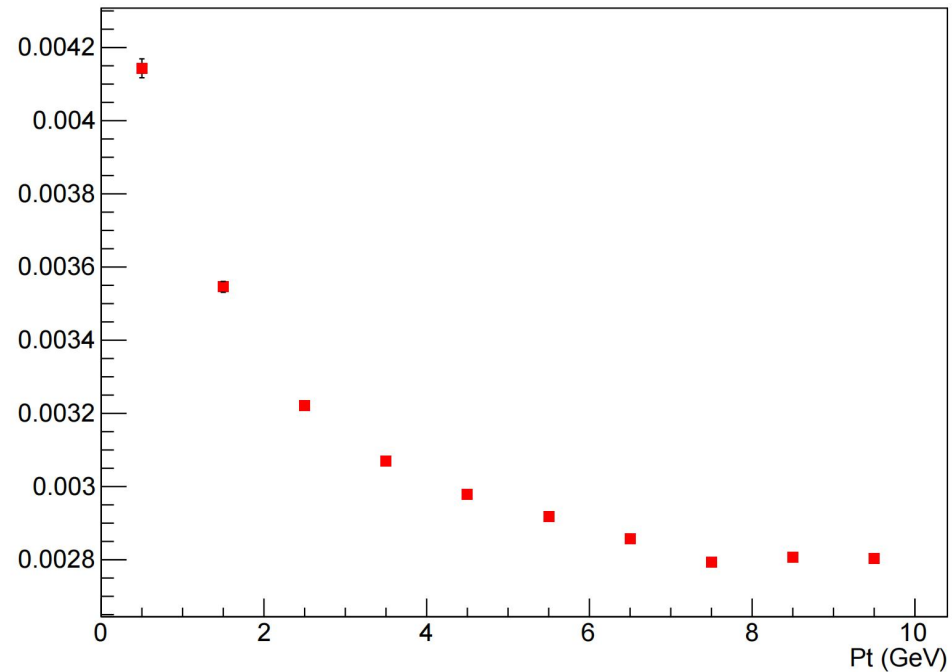
ps: There are many noisy towers in the EMCal, which take up a lot of storage. If we need to process a large number of events, we should apply an energy threshold when generating the pico DST; otherwise, we cannot be able to store many events.

dphi(truth - reco) vs pT

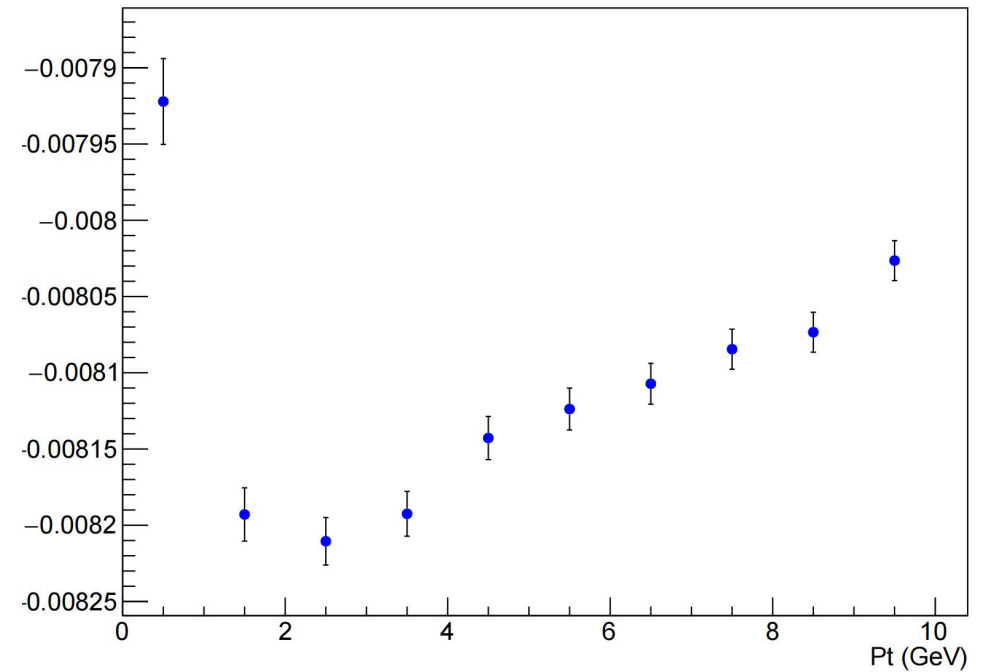


dphi(truth - reco) vs pT

Resolution (Sigma) vs Pt



Peak position vs Pt



ML4Reco

Jingyu

Event

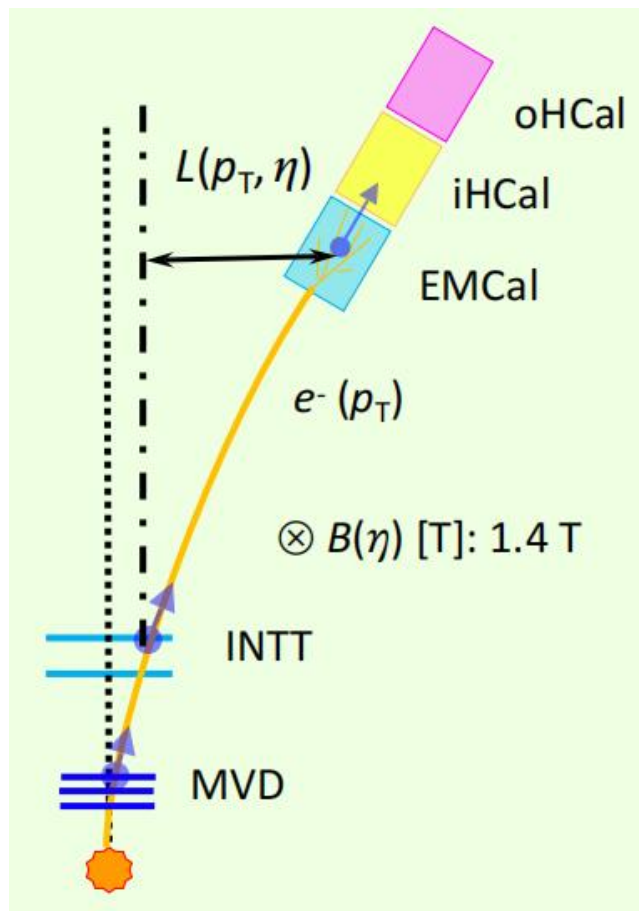
1M events simulation Based on Fun4all on sPHENIX

```
INPUTGENERATOR::SimpleEventGenerator[0] -> add_particles("e-", 1);  
INPUTGENERATOR::SimpleEventGenerator[0] -> set_vtx(0, 0, 0);  
INPUTGENERATOR::SimpleEventGenerator[0] -> set_pt_range(0, 10); // GeV  
INPUTGENERATOR::SimpleEventGenerator[0] -> set_eta_range(-1.1, 1.1);  
INPUTGENERATOR::SimpleEventGenerator[0] -> set_phi_range(-M_PI, M_PI);
```

0.5M for train and test, other 0.5M for showing performance

The data be used on showing performance is not same as train and test, no overfit in performance shown

Dataset



trk_feat: 5 hits position 5*3
inner/outer INTT only 1 clus
Select Closest Points of MVTX

calo_feat:

Calo cluster reco with inner face center,
Calo cluster reco with volume center,
9 towers that have max deposited energy (padding and cutting)

DATASETS:

X: Feat_select

Y: Truth_Pt

data scaler

if scaler is None:

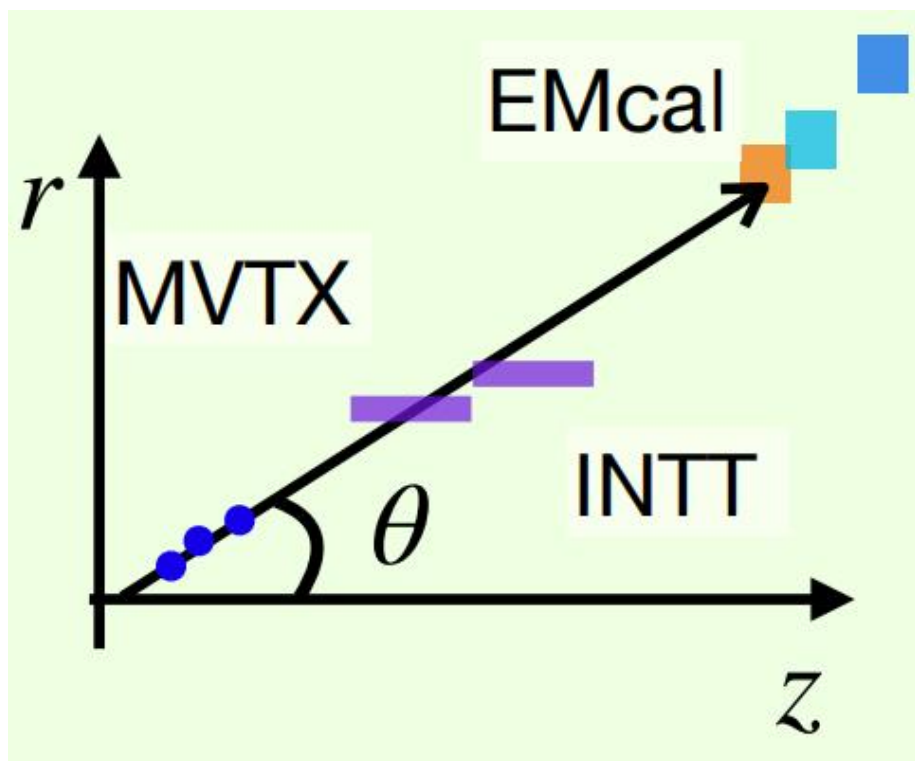
scaler = StandardScaler()

data_X = scaler.fit_transform(data_X)

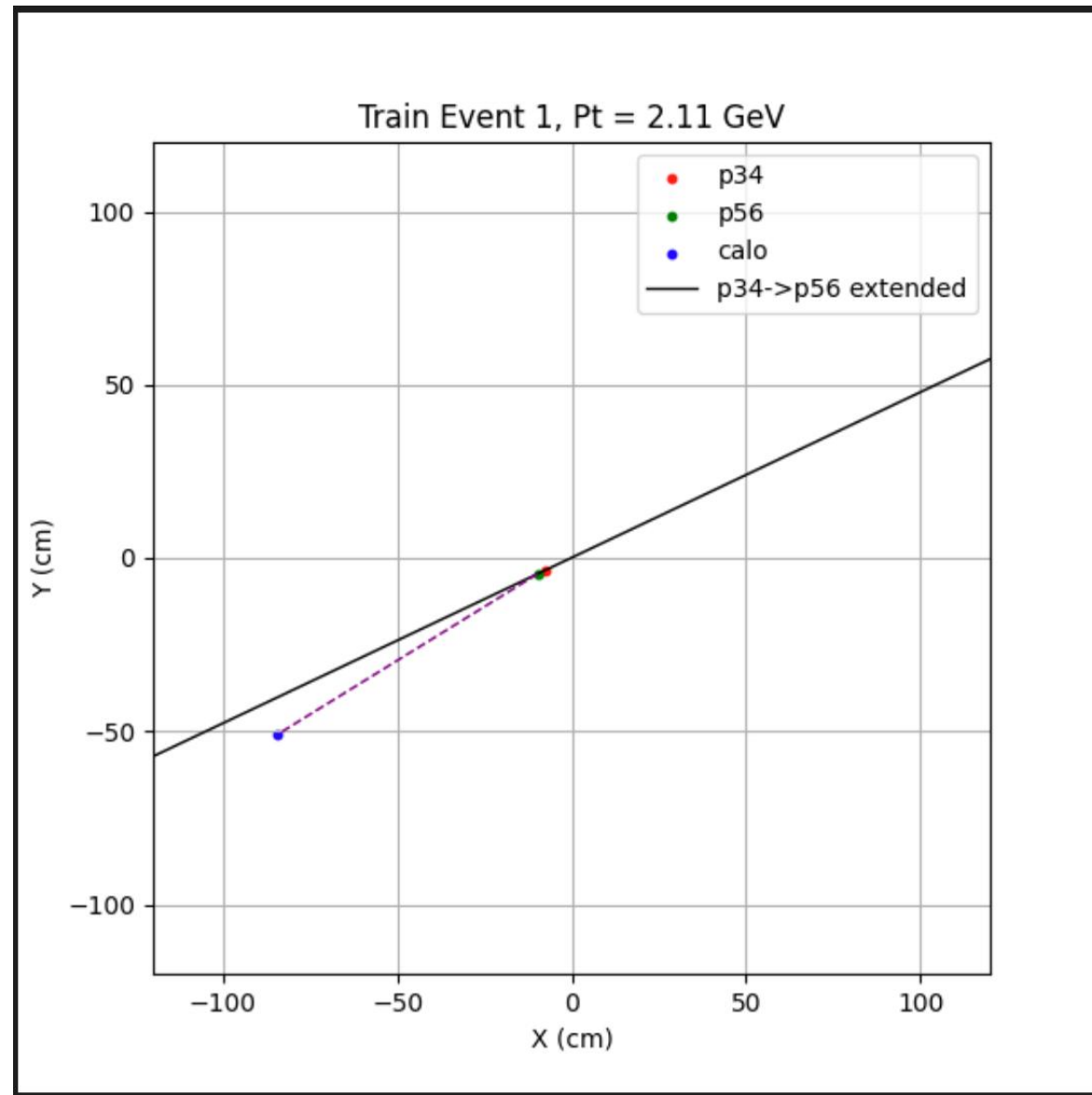
else:

data_X = scaler.transform(data_X)

Dataset



[INTT_R,Z + calo_R,Z,E]

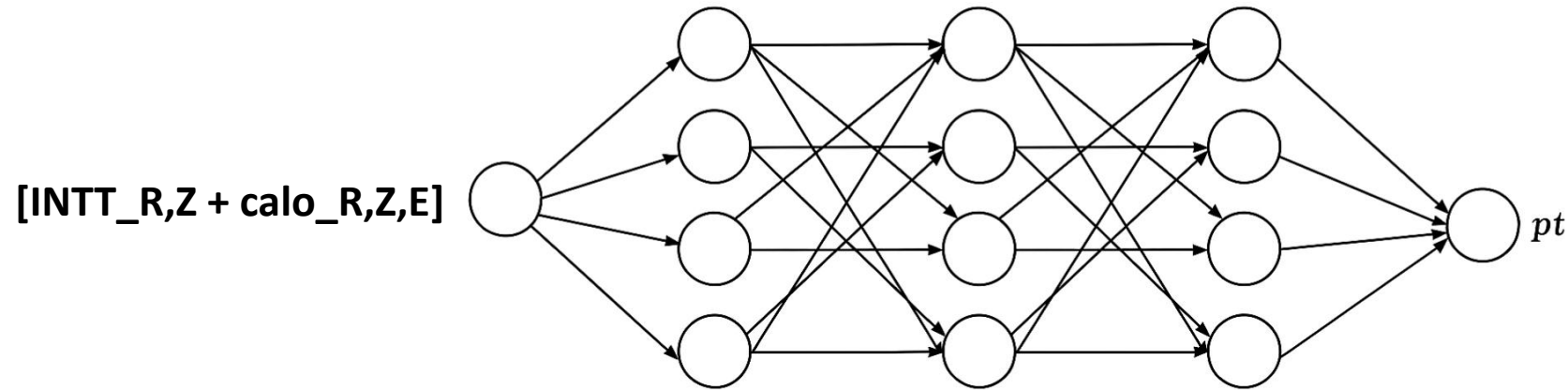


[$1/\Delta\Phi$]

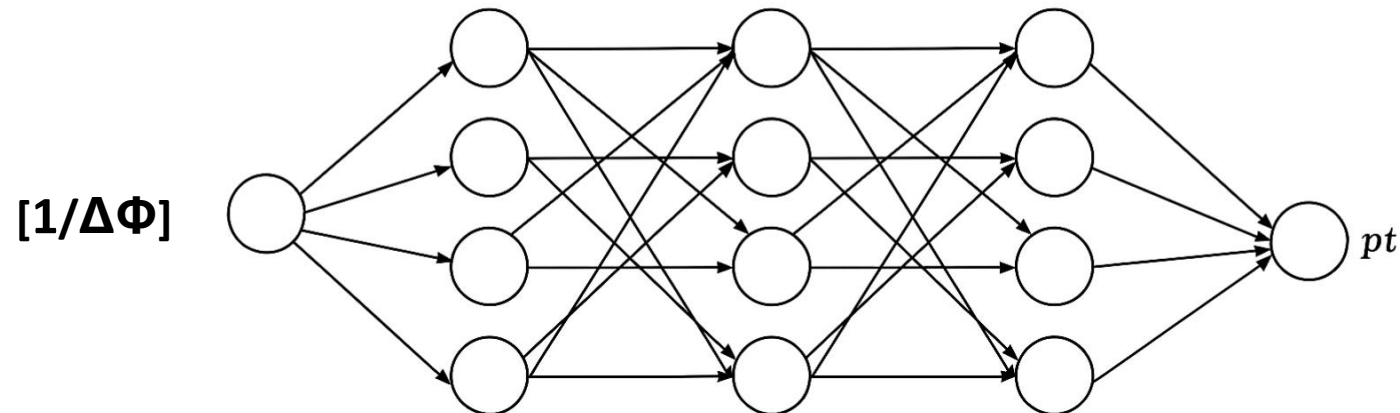
Model

In the training from angle to pt, in addition to using resolution as the loss, some additional penalty mechanism are also needed.

Therefore, a simple approach is to train separately first, and then combine the results.



MLP1: 3hidden layer, hidden_dim=256, nn.Dropout(0.2)



MLP2: 3hidden layer, hidden_dim=256, nn.Dropout(0.2)

Train_model1 - [INTT_R,Z + calo_R,Z,E]

Hyper parameters:

- batch_size=1024, epochs=200, lr=5e-5, val_ratio=0.3

Loss function:

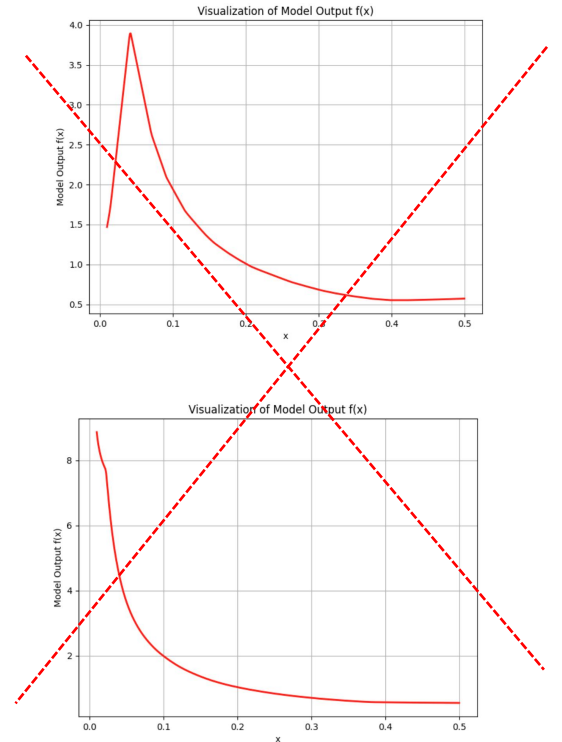
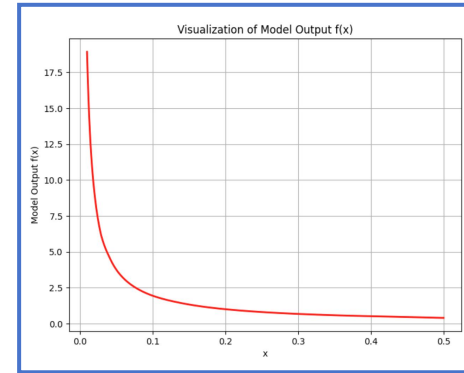
- $pt_reso = (yb - pred) / (yb + 1e-6)$ Relative resolution,
1e-6 to prevent division by zero.
- $weights = (pt_reso.abs() < 0.2).float() * 2.0 + 1.0$ Increase the weight inside the peak,
reduce the influence of outlier data points
- $loss = ((pt_reso) ** 2 * weights).mean()$ Use squared values instead of absolute values to
make the peak position closer to zero.
- if val_loss < best_val_loss: Saved best model

Train_model2 - $[1/\Delta\Phi]$

epochs=500.

Loss function:

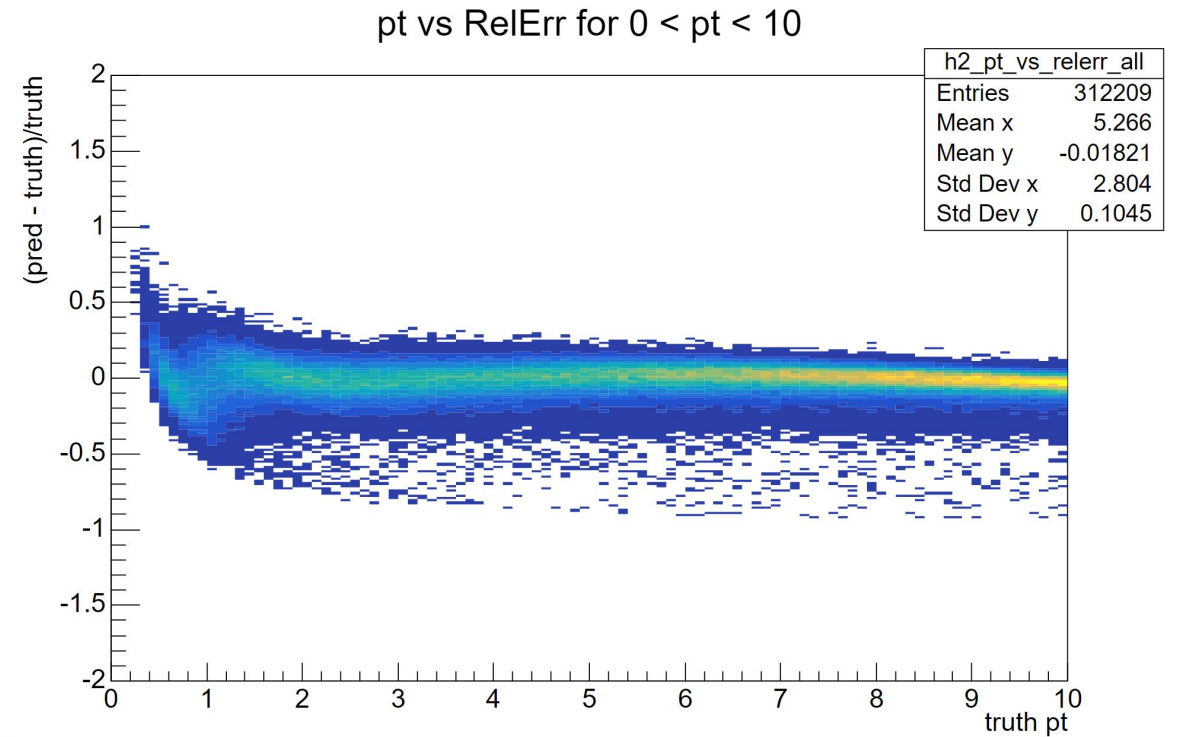
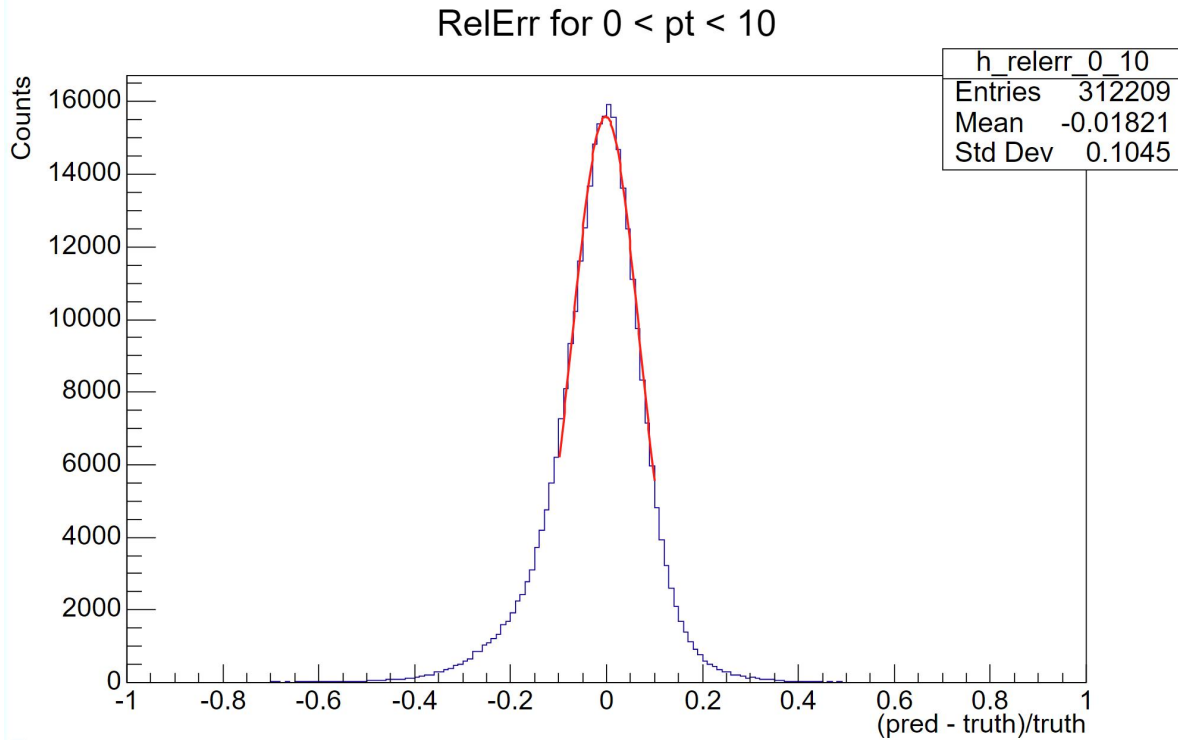
- $pt_reso = (yb - pred) / (yb + 1e-6)$
- $weights = (pt_reso.abs() < 0.2).float() * 2.0 + 1.0$
- $main_loss = ((pt_reso) ** 2 * weights).mean()$
- **monotonic_loss** **requires pt to decrease as the angle increases;**
 - $\lambda_{mono} = 0.3$ **otherwise, oscillations may occur.**
- **boundary_loss**
 - $[0.5, 1, 2, 10, 15, 25, 50, 100, 200] \rightarrow [0.0961, 0.1922, 0.3844, 1.922, 2.883, 4.805, 9.61, 19.22, 38.44]$:
 - $\lambda_{boundary} = \min(0.005 * epoch, 0.2)$
- $loss = main_loss$
- $+ \lambda_{mono} * monotonic_loss$
- $+ \lambda_{boundary} * boundary_loss$



Add boundary conditions outside the data range to ensure that the pt estimate is sufficiently elevated at small angles.

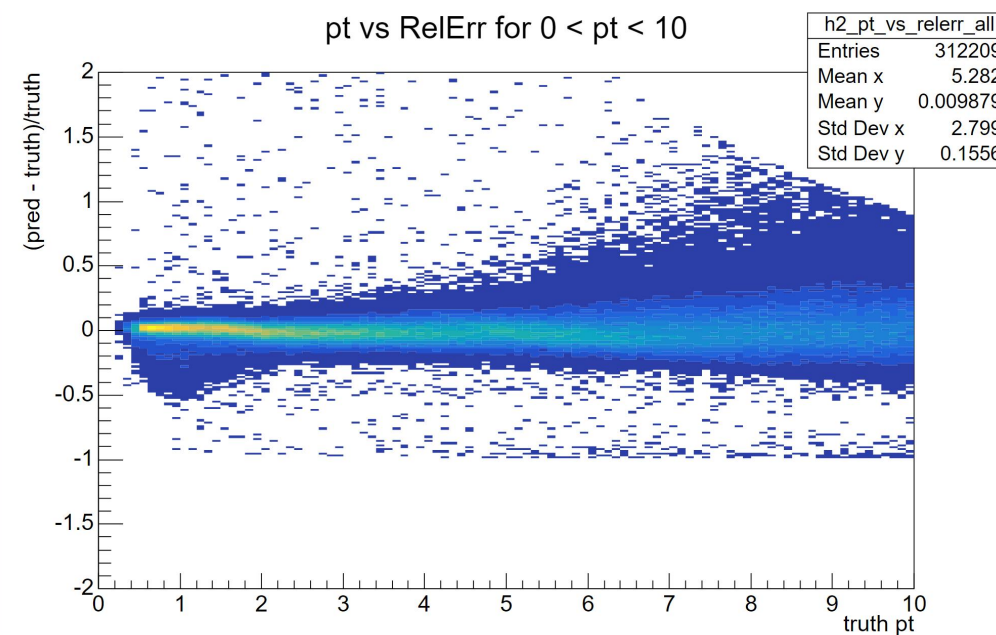
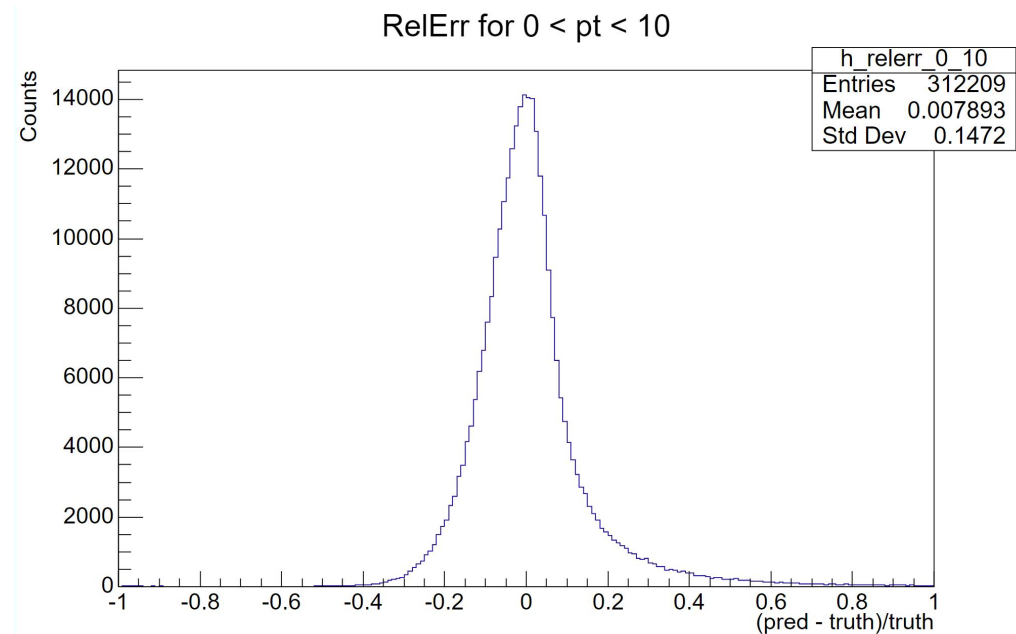
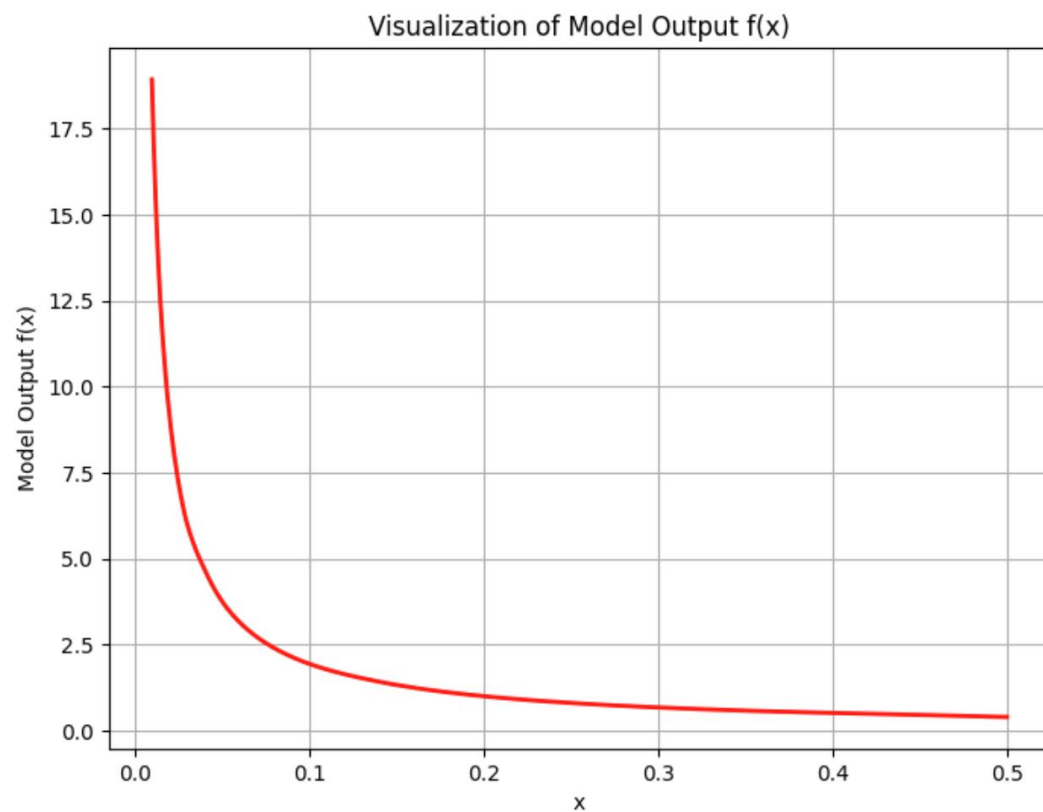
Dynamic weighting to prevent affecting data learning in the early stages.

Model1 - [INTT_R,Z + calo_R,Z,E]



Model2 - $[1/\Delta\Phi]$

model visualization



Train_combined model 1&2

X: [dphi_i, pt_pred1_i, calo_edep_i, pt_pred2_i] + pt_bin_onehot

Y: Truth_Pt

pt_est = 0.5 * (pt_dphi + pt_energy)

embed

pt_bin_edges = [0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10]

pt_bin_onehot = [0] * 10

MLP: 3hidden layer, hidden_dim=128

epochs=300

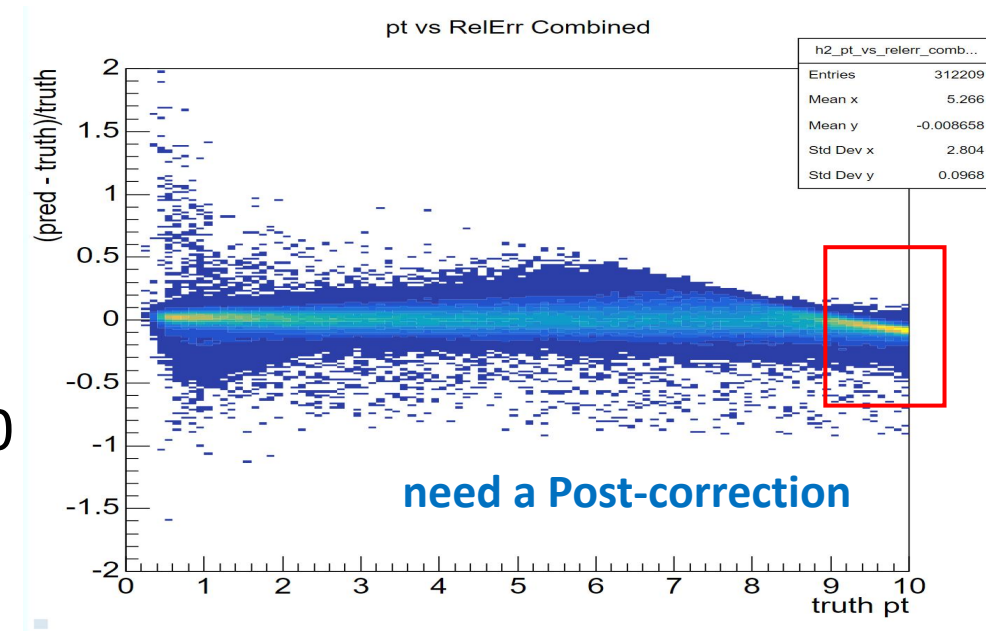
Loss:

pred = model(xb)

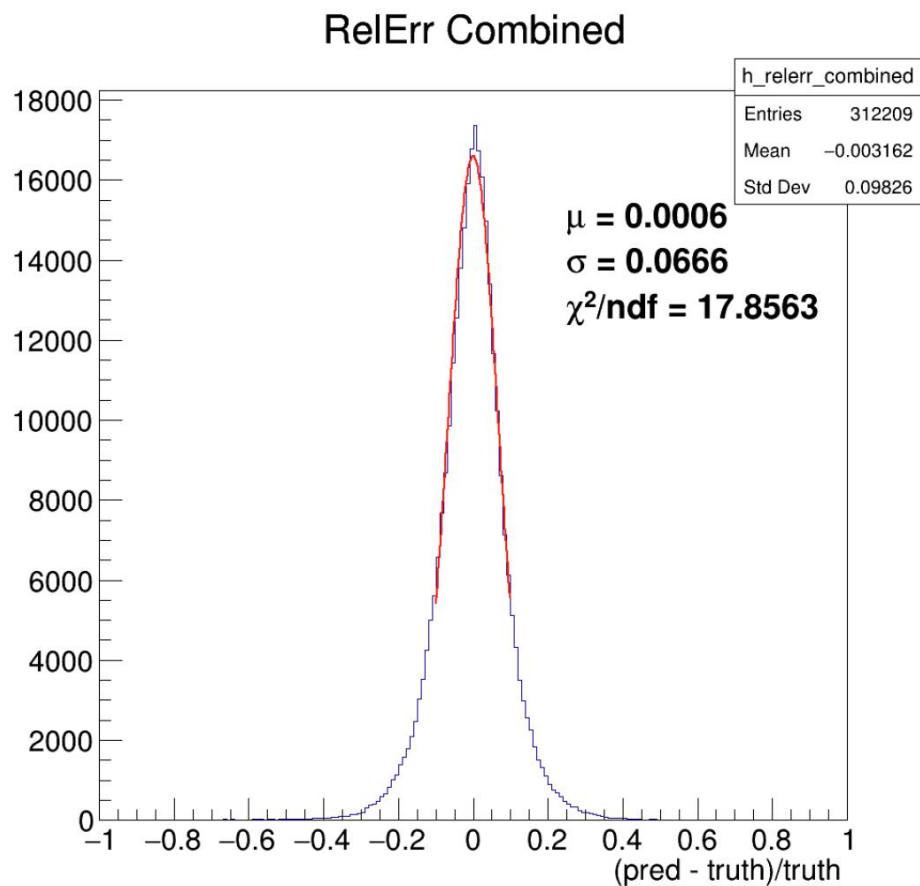
pt_reso = (yb - pred) / (yb)

weights = (pt_reso.abs() < 0.2).float() * 2.0 + 1.0

loss = ((pt_reso) ** 2 * weights).mean()



Performance

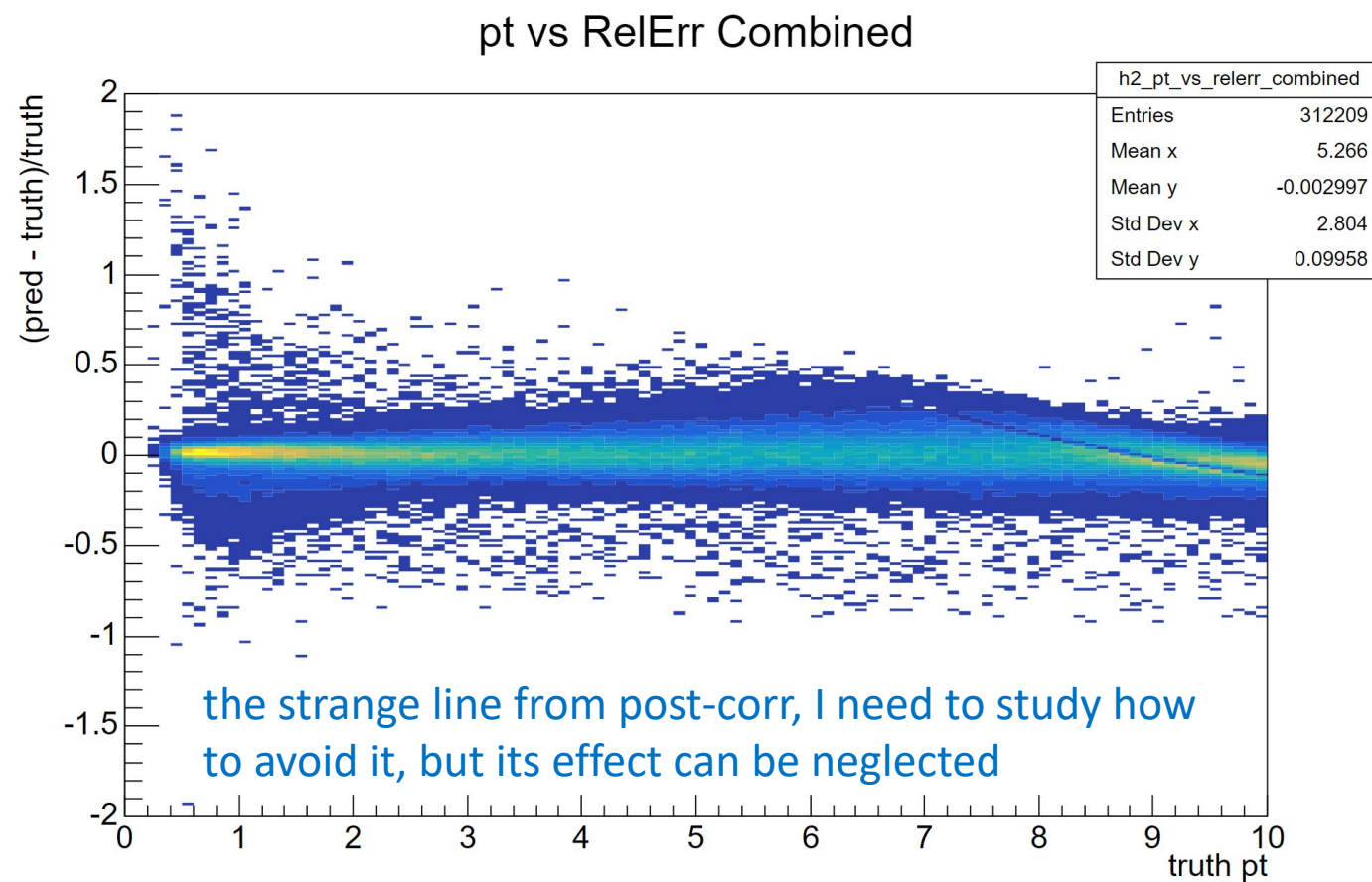


Post-correction

if reco_pt $\geq$ 8.8:

correction_factor = $0.02 + 0.08 * (\text{reco_pt} - 8.8)$

pred_np[i] = reco_pt * (1.0 + correction_factor)



Better results: Better efficiency, Better bias, Better resolution

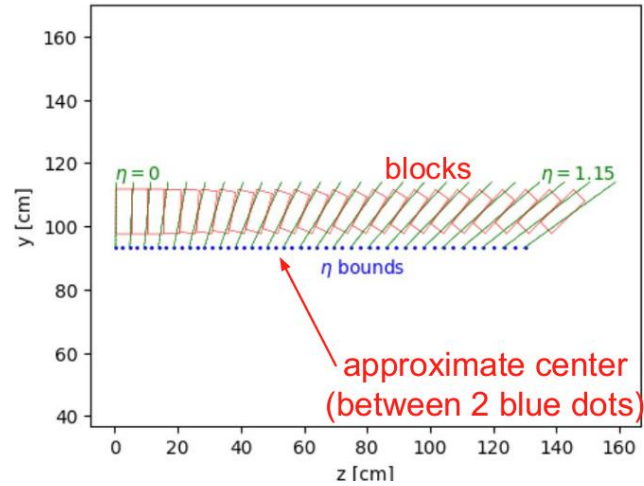
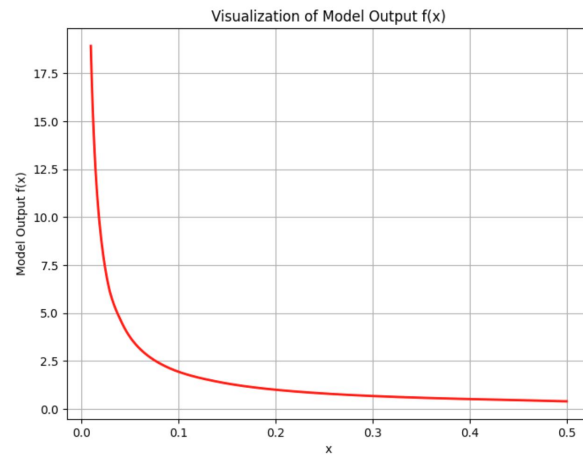
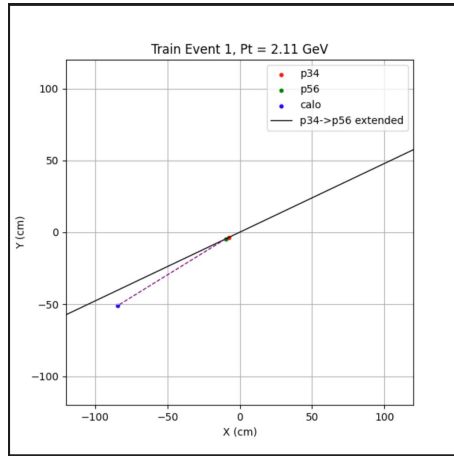
Summary

- Better efficiency: Only i-o INTT and calo have hits, with cluster deposited energy greater than 0.5 GeV.
- Better bias: The mean value and Gaussian peak are closer to zero compared to other reconstruction methods.
- Better resolution: The distribution is more symmetric, with the smallest width and the smallest standard deviation.
- The workflow, code, model configuration, hyper parameters, and post-corrections still need to be carefully checked.

Discuss on 0620

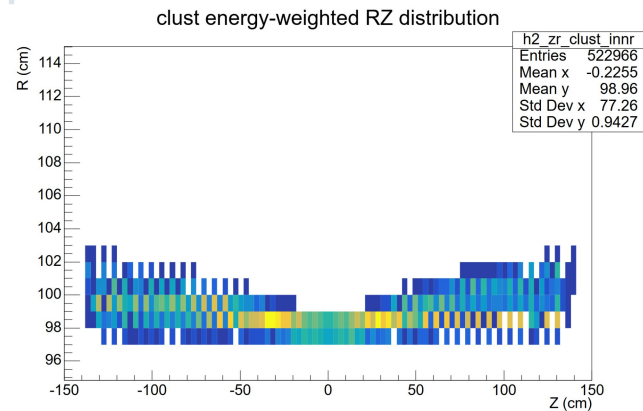
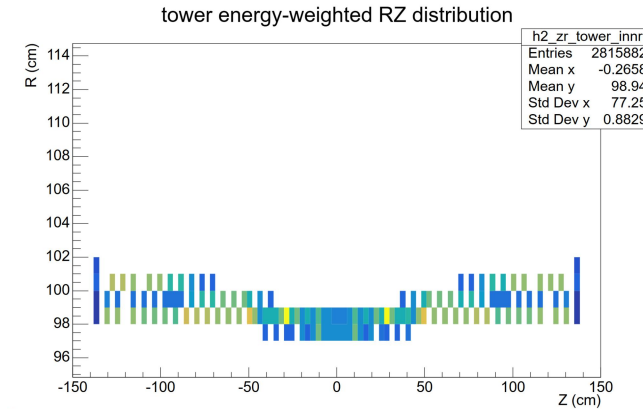
- reco and analysis on a fix R?
- a better function to require model2
- consider charge hadron into our study

Get $\Delta\phi$ from a fix R

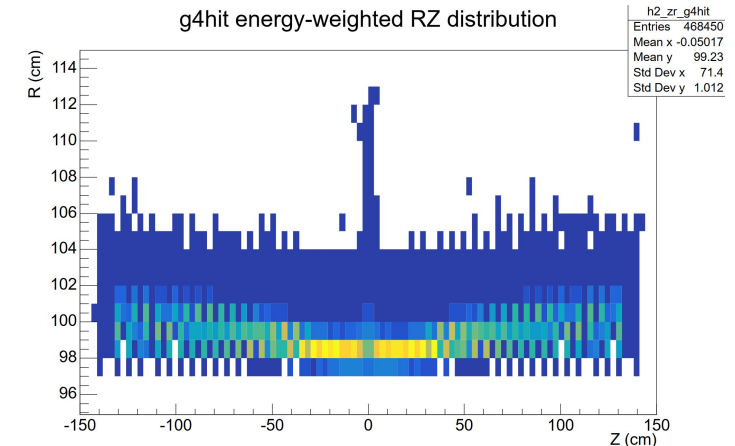


Due to the slant and sawtooth arrangement of the EMCAL towers, both the recorded hit positions and the reconstructed cluster positions are not located at a fixed radius.

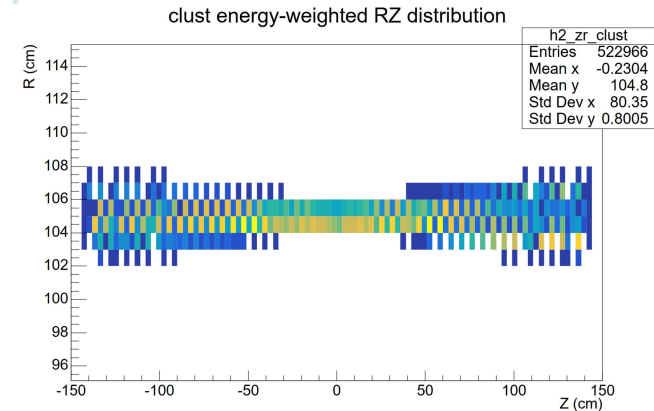
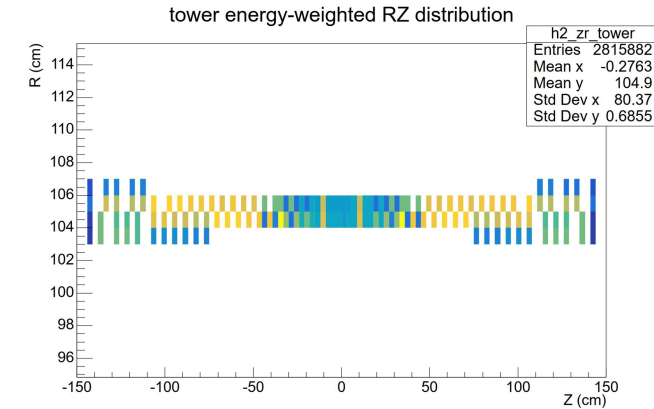
inner face:



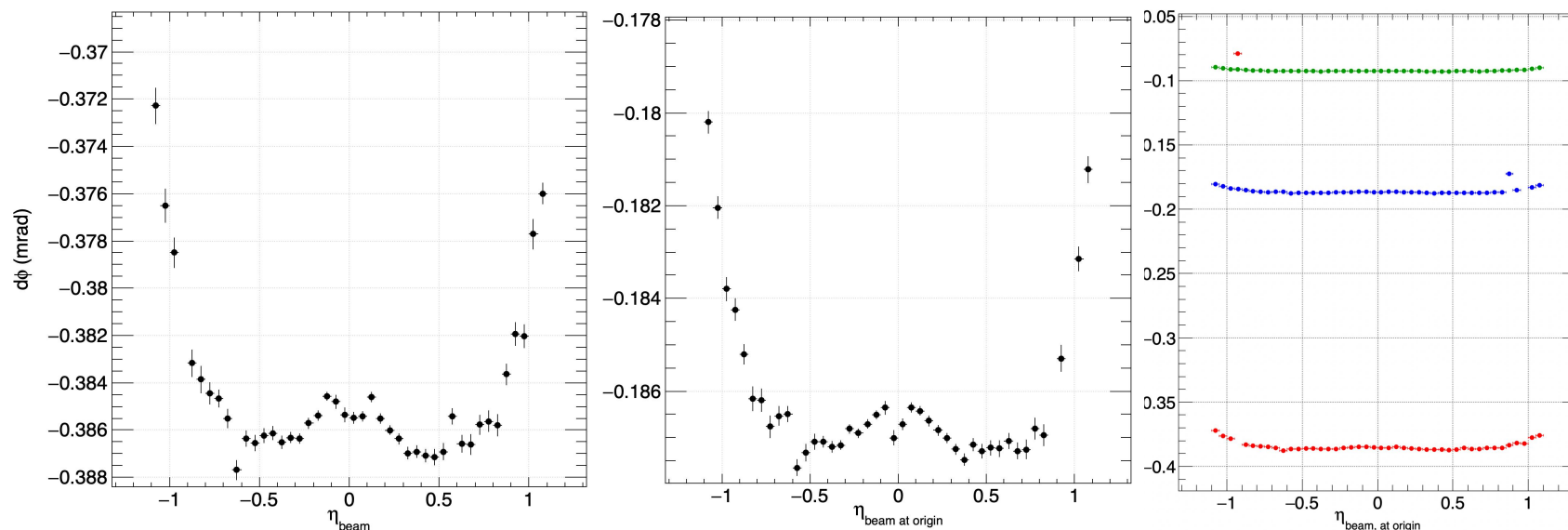
hit position:



volume center:



Genki: pt function of angel have eta dependence



[0.5, 1, 2, 10, 15, 25, 50, 100, 200]

->

[0.0961, 0.1922, 0.3844, 1.922, 2.883, 4.805, 9.61, 19.22, 38.44]

Former: $pT = 0.1922 / \Delta\phi$

Now: Maybe we need a new function consider the eta dependence and for a fix R

From the discussion on Mattermost:
we can see the dependence of pT on $\Delta\phi$, as well as its η dependence.
If there is a better function that describes pT as a function of both $\Delta\phi$ and η , I could incorporate more accurate boundary conditions, which might lead to improved results.

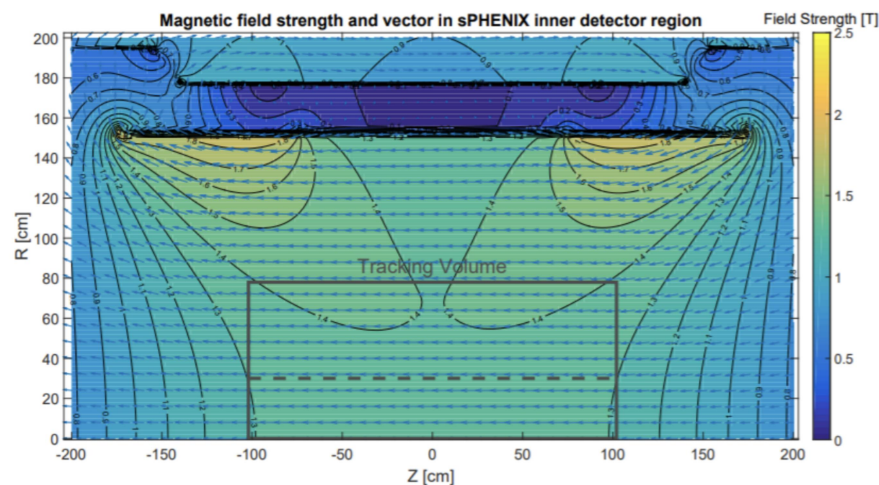
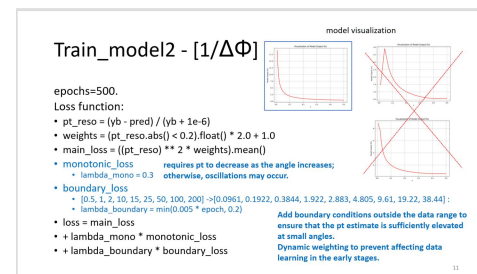


Figure 12. Field Map of the sPHENIX Solenoid



consider pion(charge hadron) into model

- Because the RCF has been quite busy recently, the jobs are running very slowly, so I still have no charge hadron simulation data.

0702

- Jingyu

Truth particle to svtxtrack and project to fix radius

you can access the code from my *Fun4All_physiTuto.C*, *TruthToSvtxTrack* and *tutorial class* on */sphenix/user/jzhang1/INTT-EMCAL/InttSeedingTrackDev/ParticleGen*

- From Primary particle momentum to def a track ([TruthToSvtxTrack I create](#))

```
TruthToSvtxTrack *t2t = new TruthToSvtxTrack();
se->registerSubsystem(t2t);
```

- code on */sphenix/user/jzhang1/INTT-EMCAL/InttSeedingTrackDev/ParticleGen/physiTuto*
- Using PHActsTrackProjection project track to a fix radius ([PHActsTrackProjection](#))

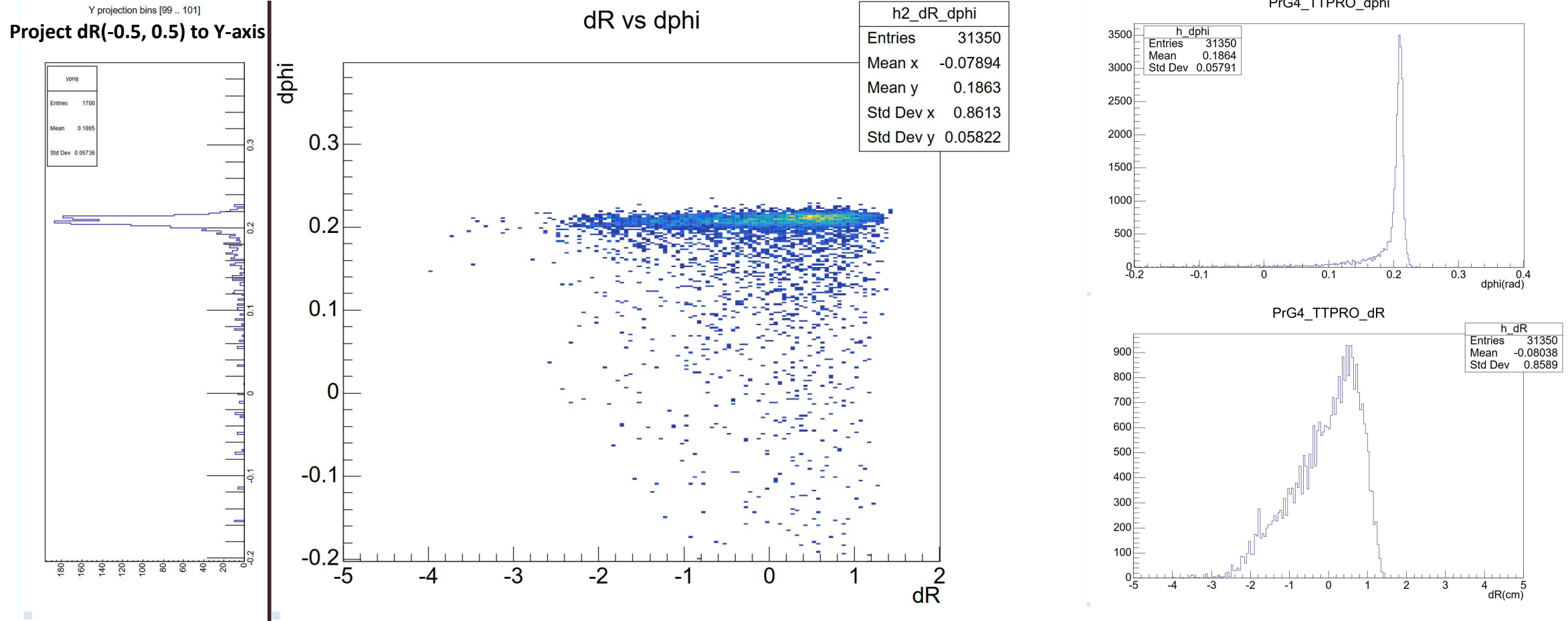
```
auto truthProjection = new PHActsTrackProjection("TruthTrackProjection");
bool doEMcalRadiusCorr = true; // Set to true to apply the radius correction
float new_cemc_rad = 99;
if (doEMcalRadiusCorr)
{
    truthProjection->setLayerRadius(SvtxTrack::CEMC, new_cemc_rad);
}
se->registerSubsystem(truthProjection);
```

- Get the track state on the radius ([prepareTruthTrack on tutorial class](#))

```
thisState = truth_track->get_state(99);
double em_x = thisState->get_x();
double em_y = thisState->get_y();
double em_r = sqrt(em_x*em_x + em_y*em_y);
double em_phi = thisState->get_phi();
double em_z = thisState->get_z();
```

Performance on 1GeV - not good

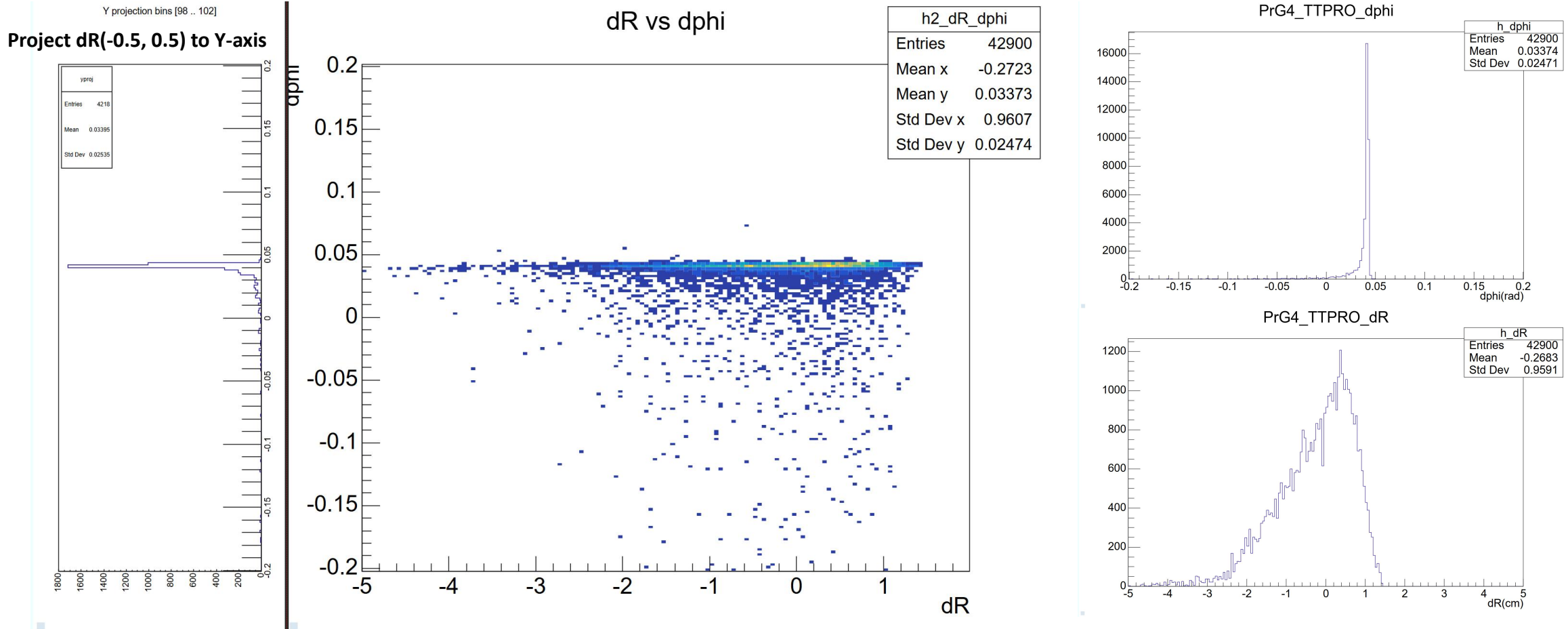
Projection position - Primary first G4hit on CEMC(truth)



PHActsTrackProjection: Magnetic field setting is const strength(1.4T)

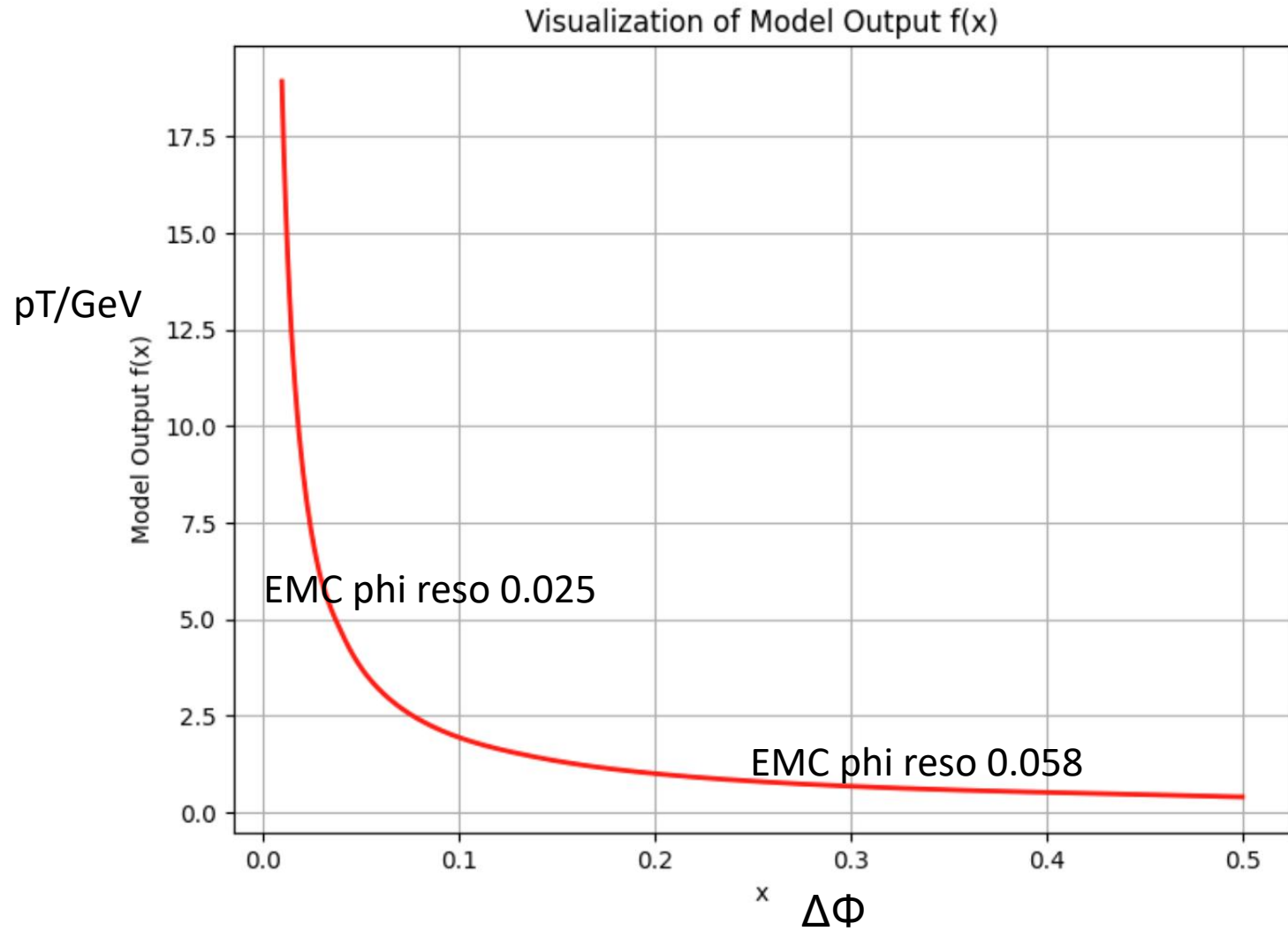
Performance on 5GeV - not good

Projection position - Primary first G4hit on CEMC(truth)



PHActsTrackProjection: Magnetic field setting is const strength(1.4T)

$p_T - \Delta\Phi$



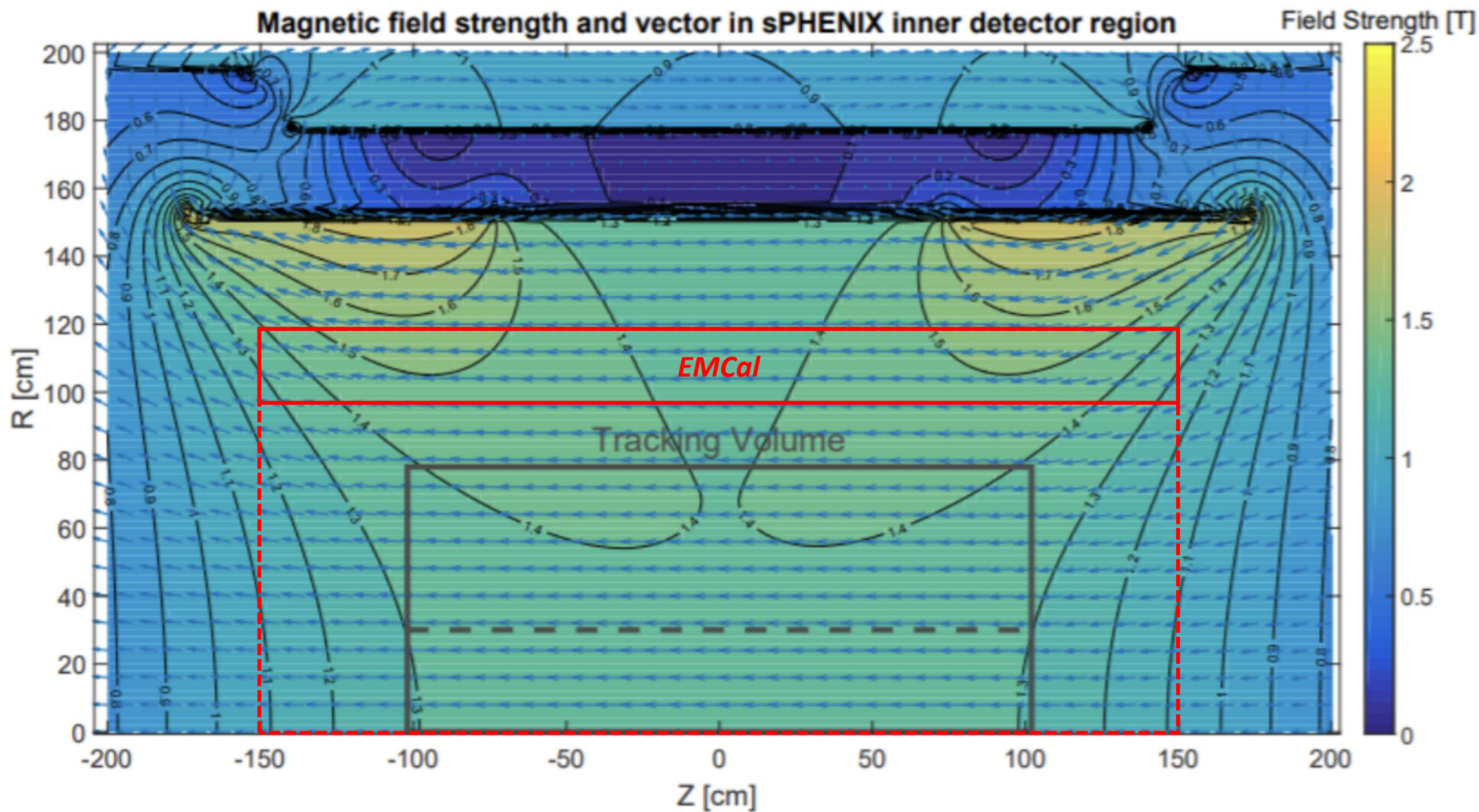
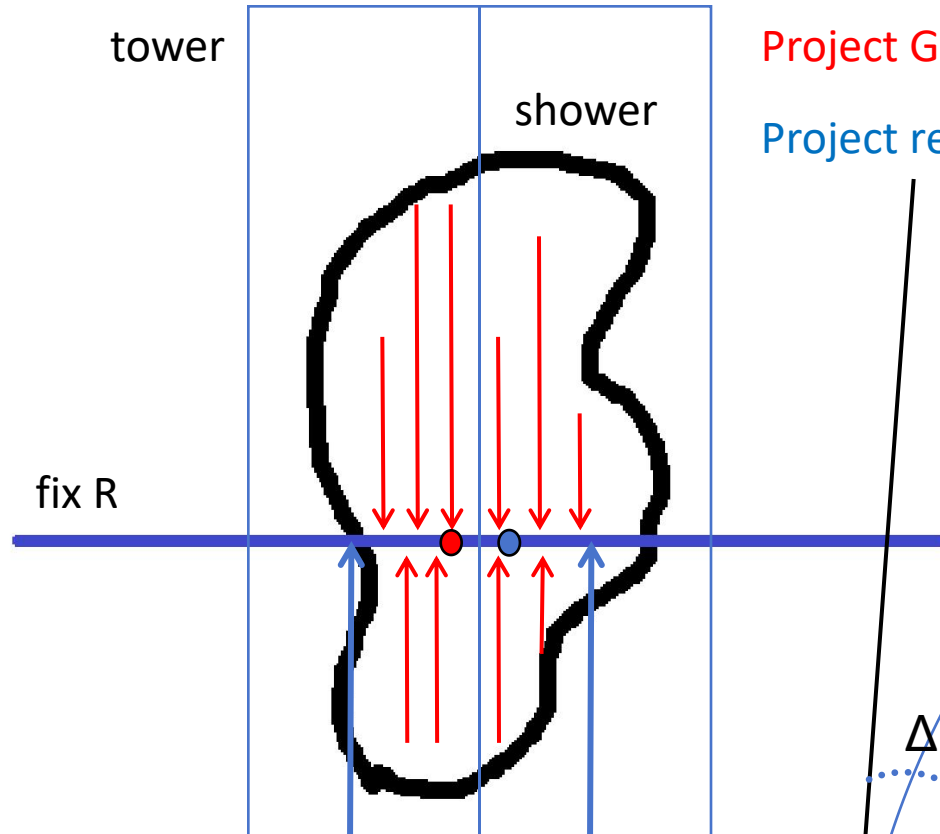


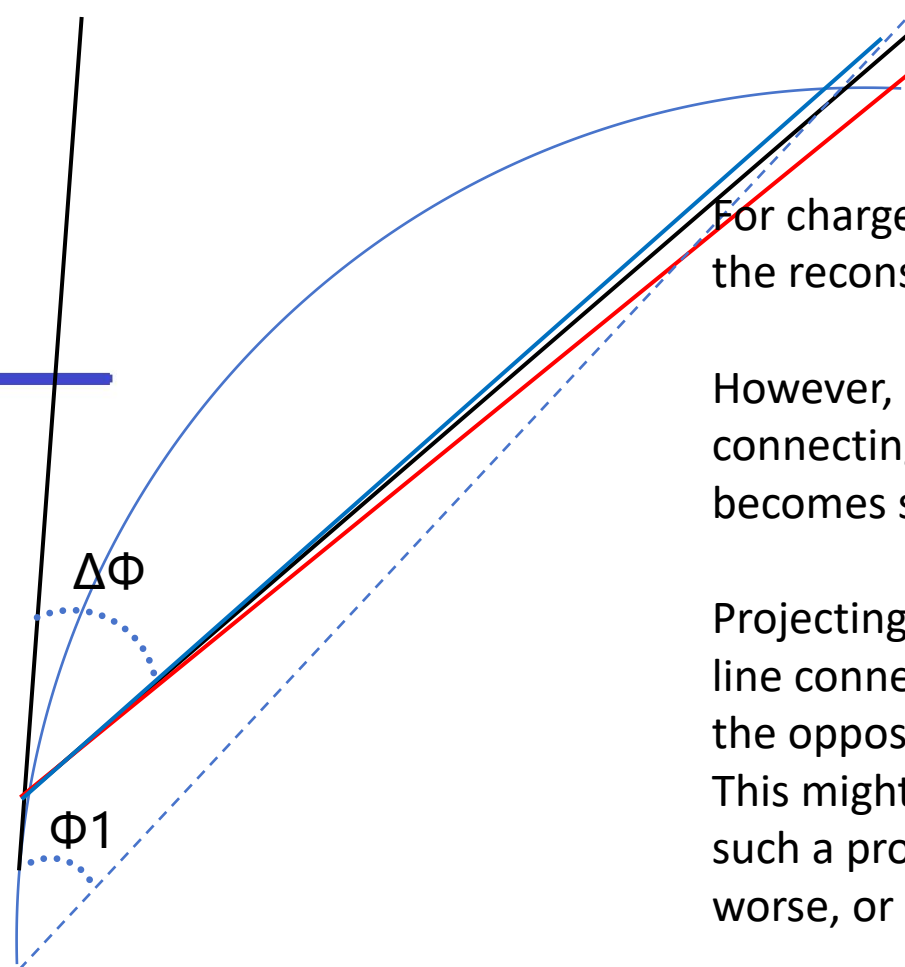
Figure 12. Field Map of the sPHENIX Solenoid

Project G4hit to fix radius and reco the center



Project G4hit to the fix R def the truth postion

Project reconstruted positon to the fix R def the emcal reco postion



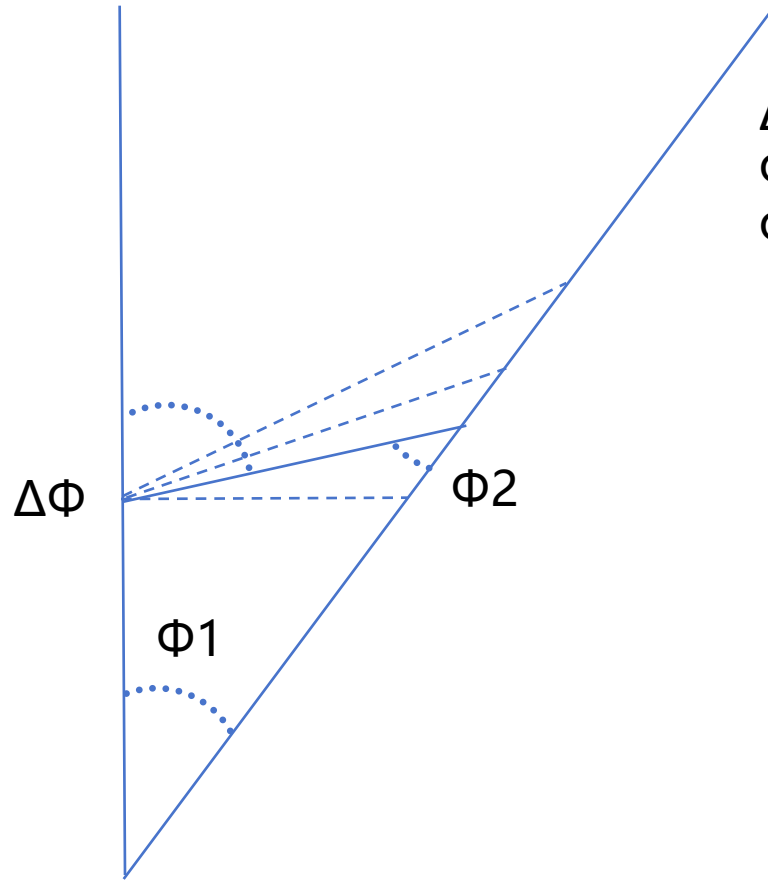
For charged track, $\Delta\Phi$ is expected to increase as the reconstruction radius increases.

However, if the projection is made along the line connecting the vertex and the EMCal, $\Delta\Phi$ actually becomes smaller as the radius increases.

Projecting the position to a fixed radius along the line connecting the vertex and the EMCal leads to the opposite result.

This might not be a good approach (in my opinion, such a projection could make the reconstruction worse, or at least not any better).

The geometry relationship



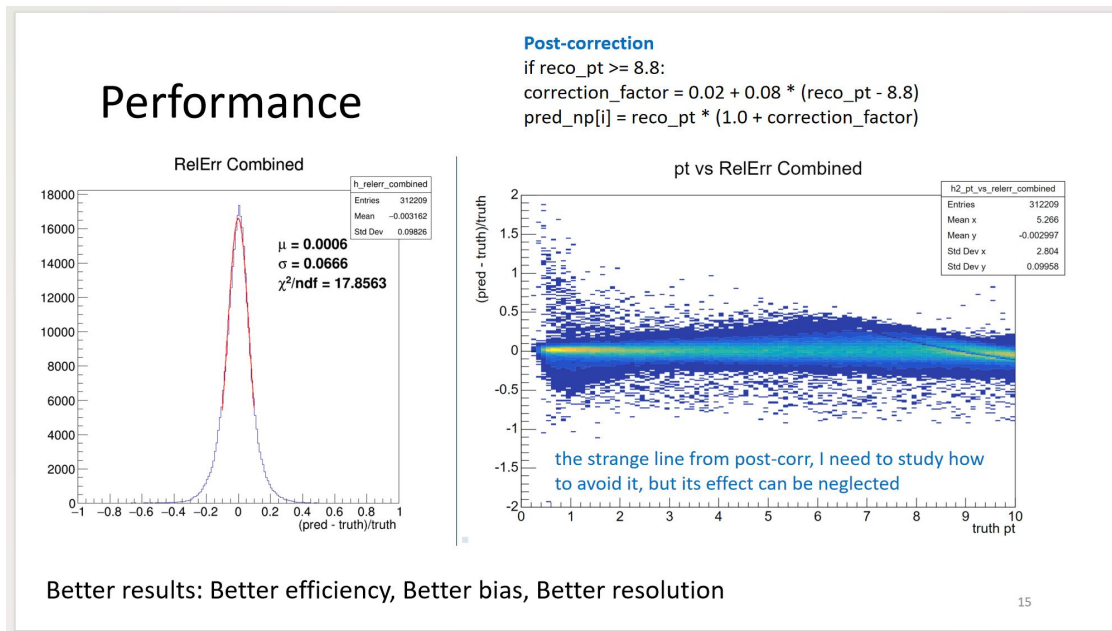
$$\Delta\Phi = \Phi_1 + \Phi_2$$

Φ_1 is constant with radius larger

Φ_2 will smaller with radius larger

Plan

- Continue to study the position reco and learn a better model
- Compare and plot the various method reco performance
 - x-axis is truth pt, y-axis is pt resolution, diff. line to plot each method
- Consider the charge hadron reconstruct to apply for event data



We have a 6% resolution for electron reconstruction in the 0–10 GeV range (we can improve the range to higher pt). we need a not-too-bad reco of charged hadrons, to perform eid. Pick out and reco electrons from charged tracks with 6% (will be better) resolution.

Try some simple electron-related reconstructions (such as photon conversions, K mesons, etc.) to prove that our work enables the data without TPC can be used to some physical analysis.

Thanks